

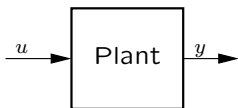
Outline

- 1 Introduction
 - Feedback basics
 - Coupled-bunch instabilities and feedback
- 2 Beam Control
 - Bunch Cleaning
 - Selective Transient Excitation
- 3 Diagnostics
 - Beam Transfer Function
 - Tune Measurement

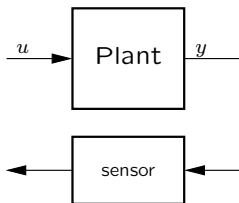


Closed-loop Feedback: Structure and Example

- Start with a physical system (plant).

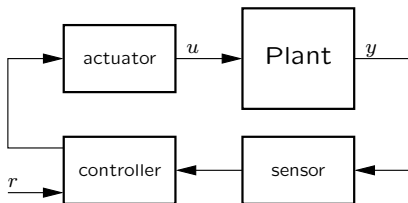


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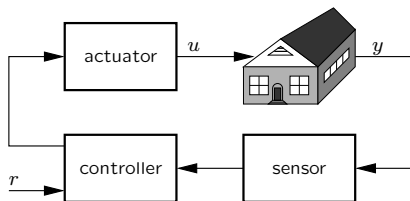
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- Measure some property of the plant with a sensor.

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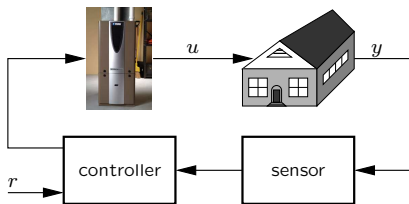
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- Measure some property of the plant with a sensor.
- Plant behavior (state) can be affected by an actuator.
- Feedback loop is completed by a controller.

Closed-loop Feedback: Structure and Example



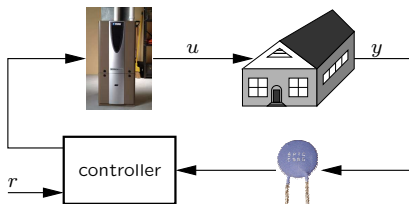
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 - Our plant is the house.

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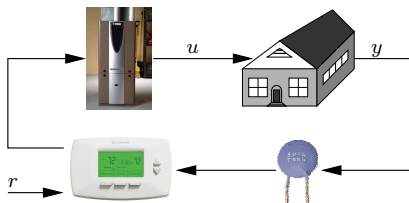
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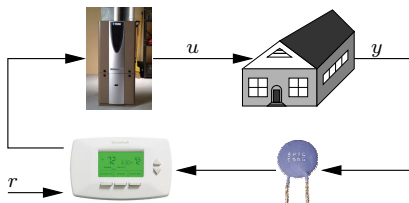
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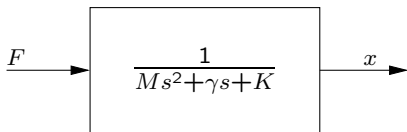
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 - Controller - thermostat.

Closed-loop Feedback: Structure and Example



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 - Our plant is the house.
 - Actuator - furnace.
 - Sensor - thermistor.
 - Controller - thermostat.
- Loop signals
 - Output y - temperature;
 - Input u - heated air from the furnace;
 - Reference r - temperature setpoint.

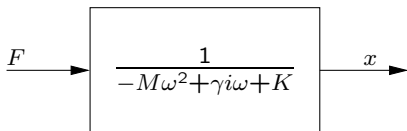
Dynamic System Descriptions and Models



- Mechanical system: mass on a spring with a damper.
- Described by $M\ddot{x} + \gamma\dot{x} + Kx = F$.
- Differential equation is a time-domain description.
- Frequency domain - Laplace transform.
- Frequency response evaluated at $s = i\omega$.



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Coupled-bunch Instabilities

- Consider a single bunch in a lepton storage ring.
- Centroid motion has damped harmonic oscillator dynamics.
- Multiple bunches couple via wakefields (impedances in the frequency domain).
- At high beam currents this coupling leads to instabilities.
- In modern accelerators active feedback is used to suppress such instabilities.



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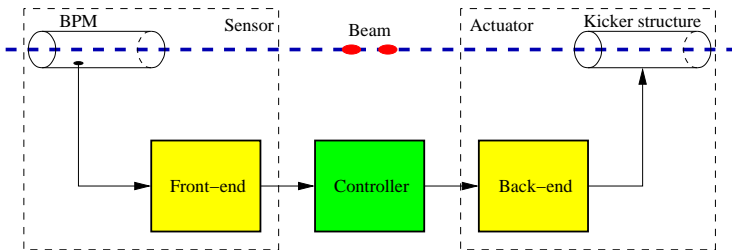
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Bunch-by-bunch Feedback

Definition

In **bunch-by-bunch feedback approach** the actuator signal for a given bunch depends only on the past motion of that bunch.



- Bunches are processed sequentially.
- Correction kicks are applied one or more turns later.

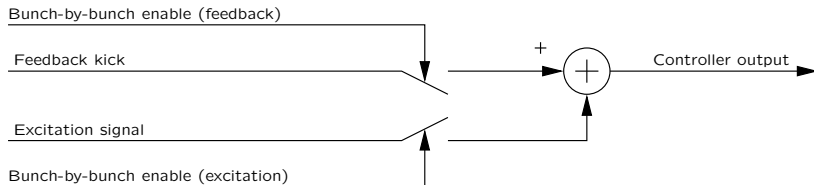


Coupled-bunch Instabilities: Eigenmodes and Eigenvalues

- If we consider bunches as coupled harmonic oscillators, a system of N bunches has N eigenmodes.
- Without the wakefields these modes have identical eigenvalues determined by the tune and the radiation damping.
- wakefields (impedances) shift the modal eigenvalues in both real part (damping rate) and imaginary part (oscillation frequency).



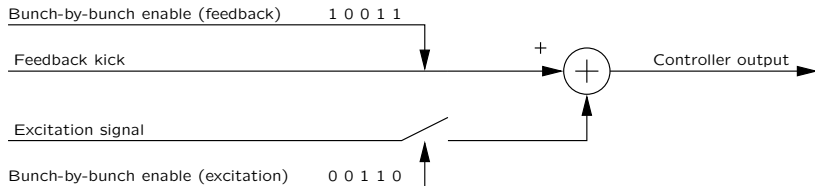
System Flexibility



- Within the controller we combine two streams: feedback and excitation;
- Bunch-by-bunch masking;
- Opens up a wealth of control and diagnostic techniques that are difficult, if not impossible, with other means.



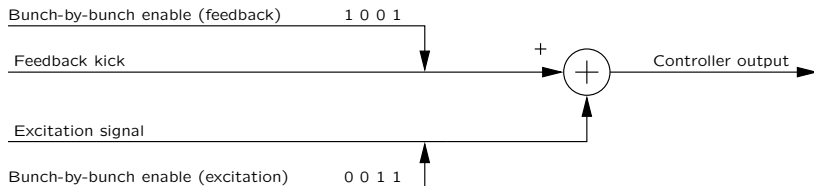
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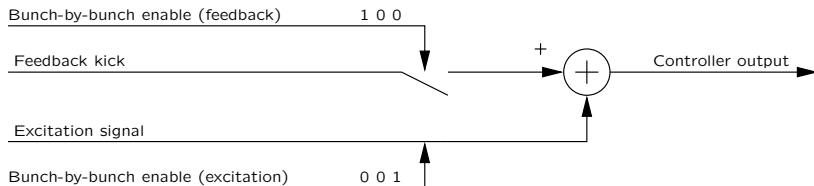
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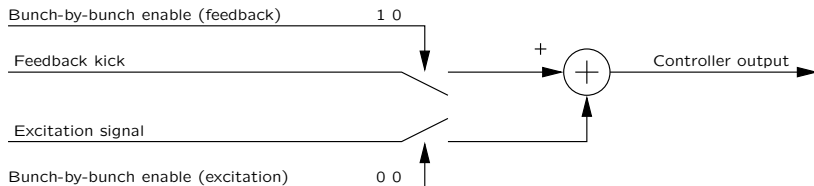
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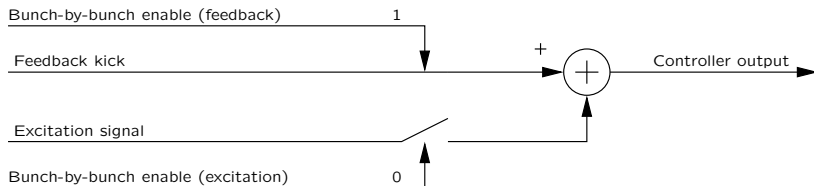
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Bunch cleaning capability in a lepton storage ring is a way to remove all charge from an arbitrary subset of RF buckets, without disturbing bunches excluded from such a subset.

Many applications:

- Cleaning up injection errors;
- Controlling diffusion from filled to empty buckets;
- Creating single-bunch fill patterns in storage rings without single-bunch injection capability;
- Creating arbitrary fill patterns for studying detector responses, etc.



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General Approach

- Keep negative feedback on the bunches to retain;
- Turn off the feedback on the bunches to clean;
- Apply to these bunches a swept sinewave excitation centered on the tune frequency;
- When excitation sweeps across the betatron resonance, bunches are driven to large transverse amplitudes and scraped off;
- Excitation frequency sweep must cover the full range of tune variations with beam current and amplitude.



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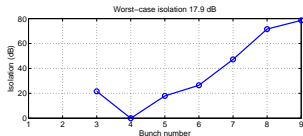
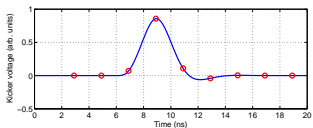
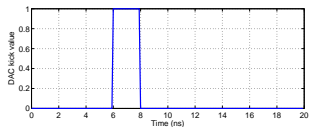


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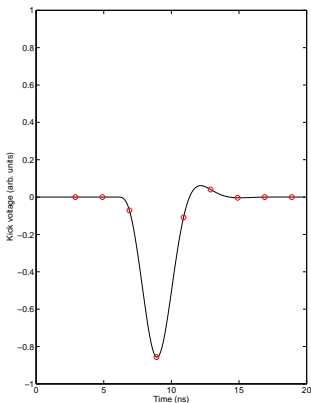
Kicking One Bucket



- Kick a single bucket (2 ns);
- DAC, amplifier and striplines stretch the kick, thus coupling to the neighboring buckets;
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- Pre-distort the kick to improve the isolation;
- Negative feedback on the neighboring bunches automatically settles on the kick pattern that minimizes the perturbation of these bunches.



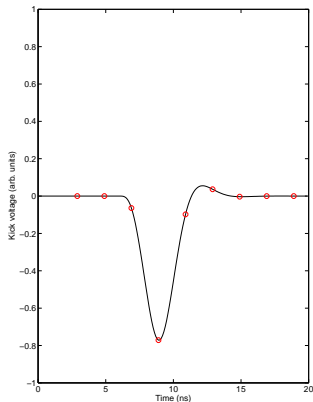
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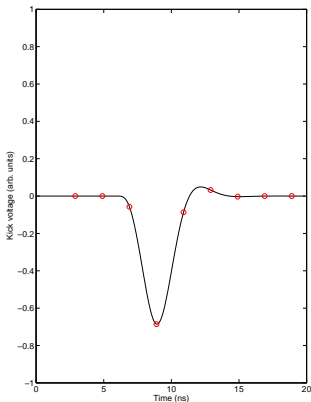
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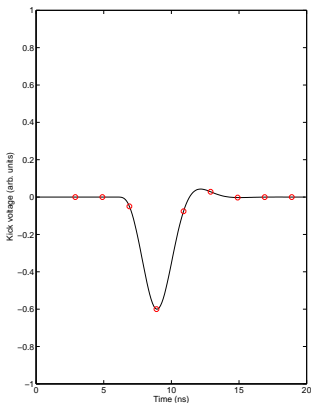
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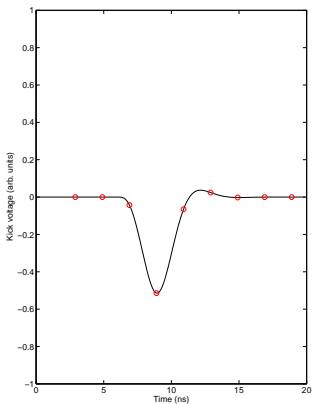
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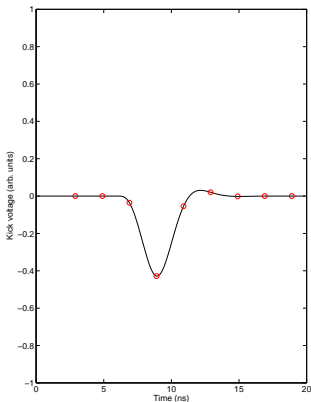
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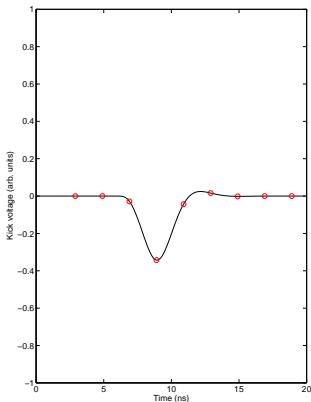
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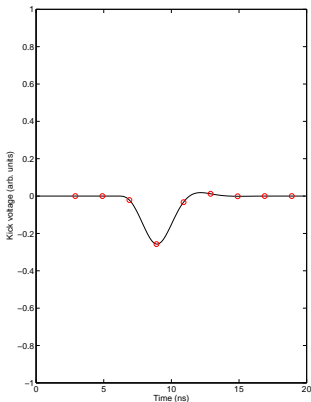
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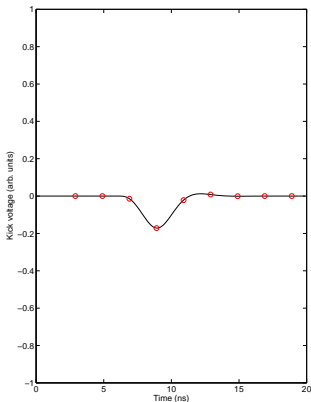
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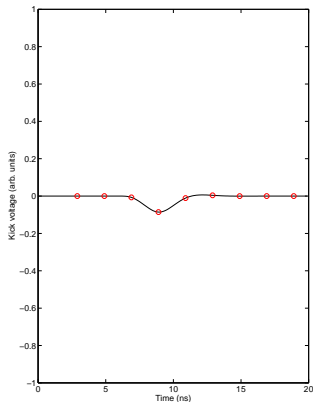
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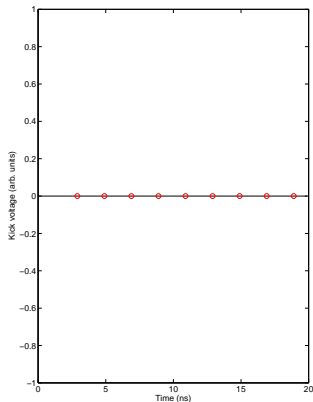
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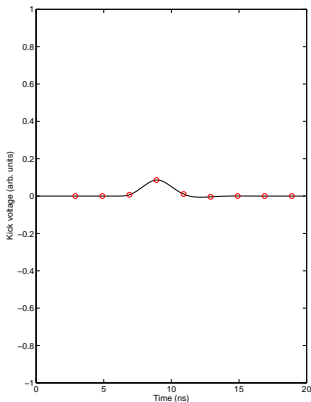
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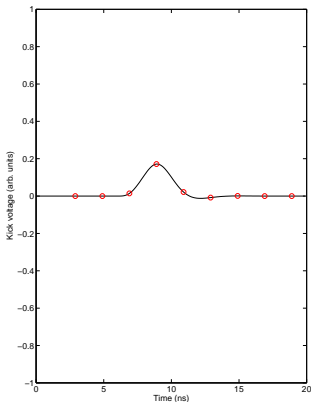
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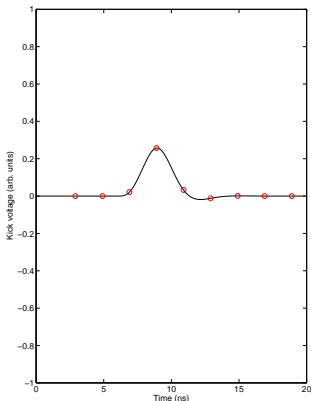
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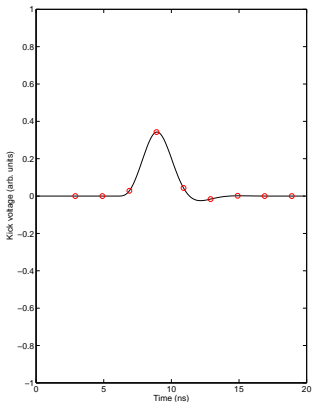
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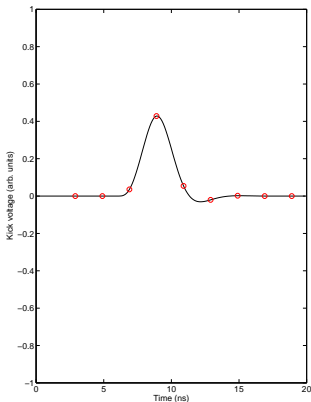
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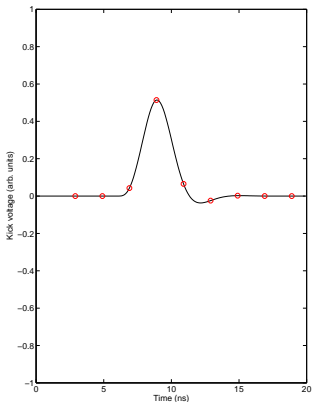
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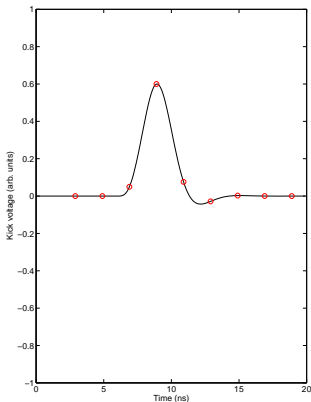
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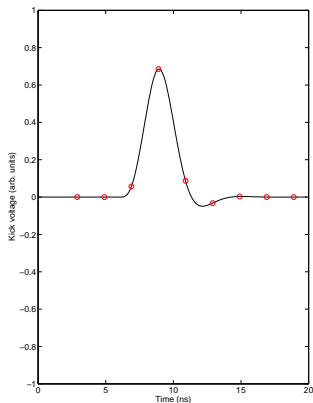
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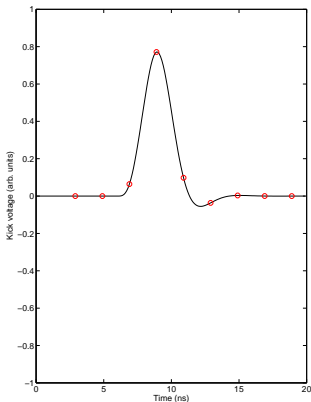
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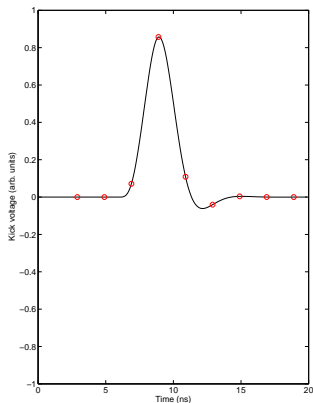
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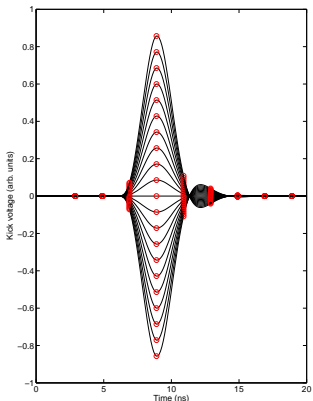
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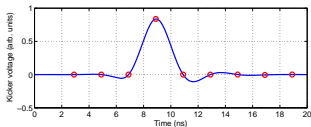
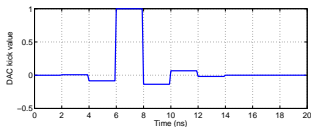


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- Kick a single bucket (2 ns);
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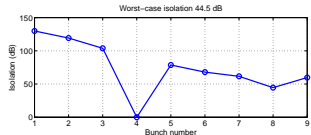
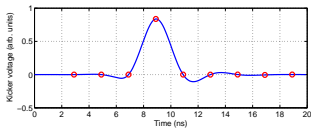
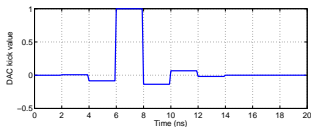
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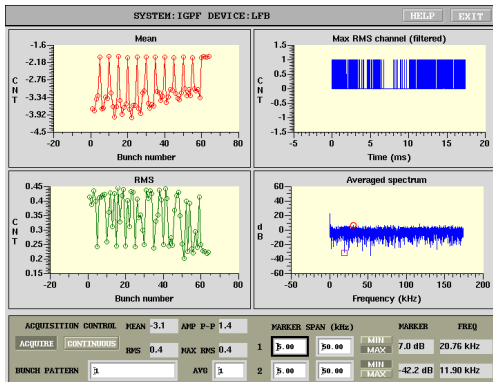
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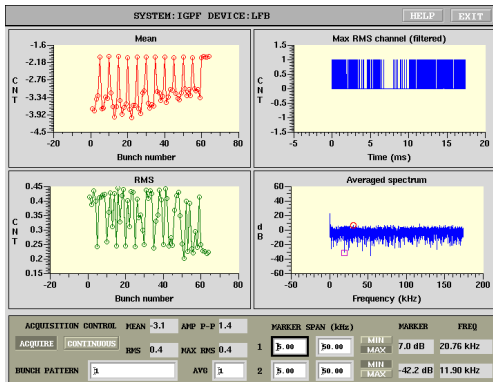
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- Excitation in the vertical plane;
- Specified cleaning of every fifth bucket.

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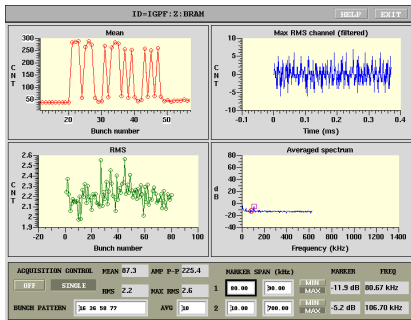
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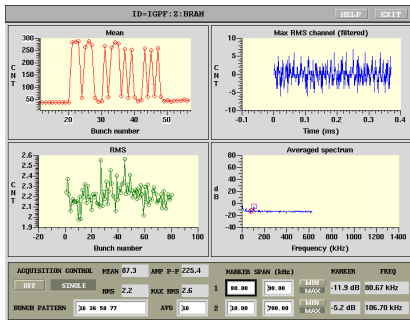
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- With the back-end optimized see good isolation bunch-to-bunch;
- Spelling MLS in Morse code here.

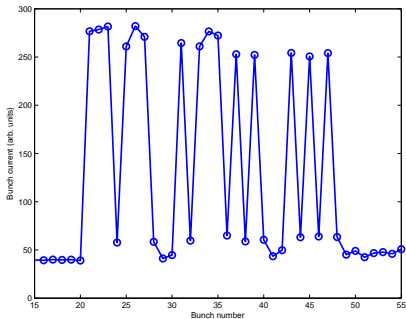


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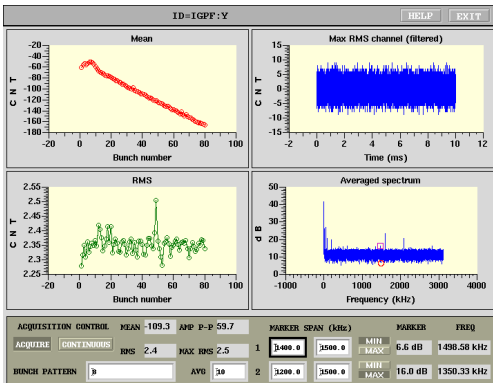
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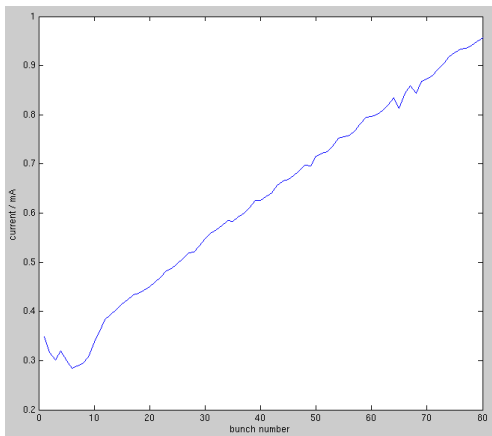
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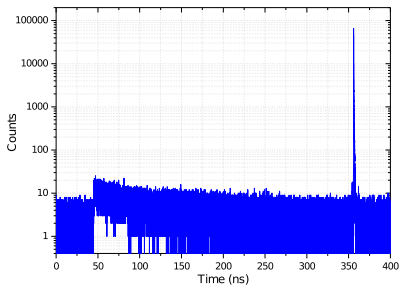
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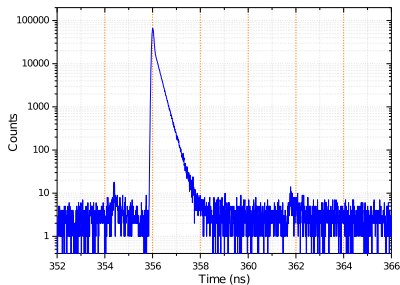
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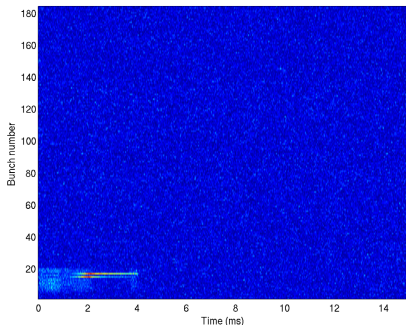


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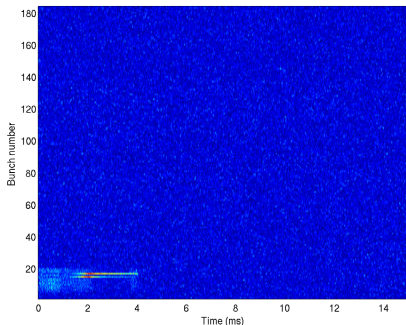
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- Modulate excitation signal on/off together with transient measurements;
- Example from ANKA: 20 bunches driven for 4 ms with feedback turned off;
- Bunch 15 spectrogram;
- Excitation sweeps through the betatron frequency.



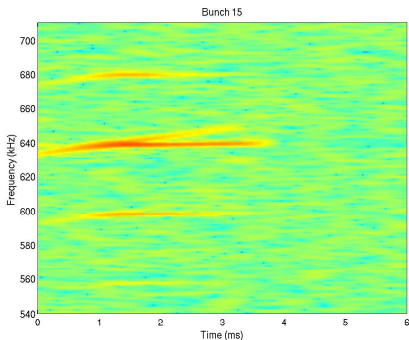
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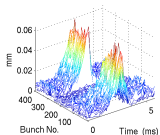


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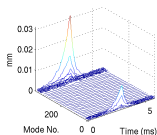


BESSY II Horizontal Grow/Damp Measurement

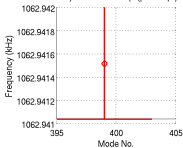
a) Osc. Envelopes in Time Domain



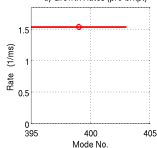
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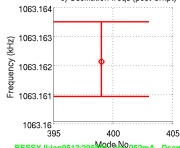
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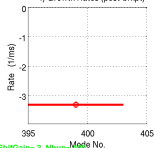
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e) Oscillation freqs (post-brkpt)



f) Growth Rates (post-brkpt)

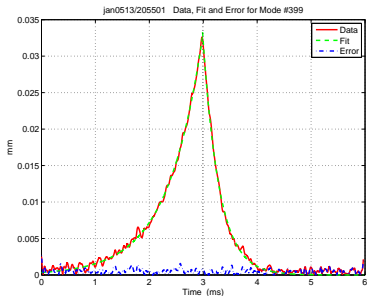


- Horizontal grow/damp at -3.0 units, 245 mA, no camshaft;
- Mode -1;
- Very fast damping;
- Excellent fit.

BESSY II: jan0513/2055000 - 252mA, Dsamp=1, ShfGain=3, Nburn=1000000
At Fs: G1= 52.7247, G2= 0, Ph1= 1.4513, Ph2= 0, Brkpts= 3732, Calib= 156.9839.

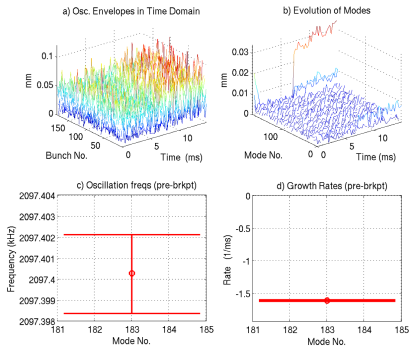


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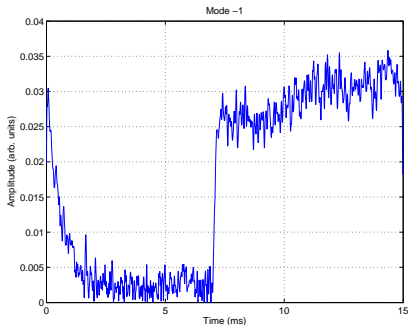
Measuring Stable Eigenmodes: ANKA X, 2.5 GeV



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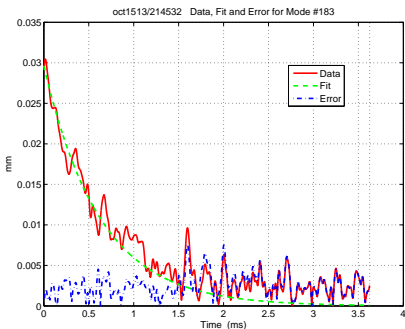
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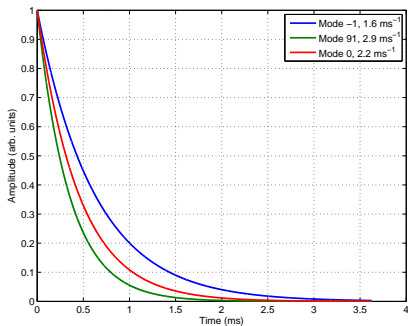


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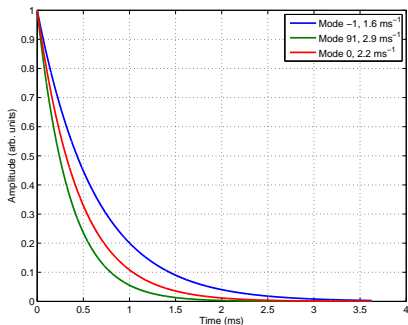
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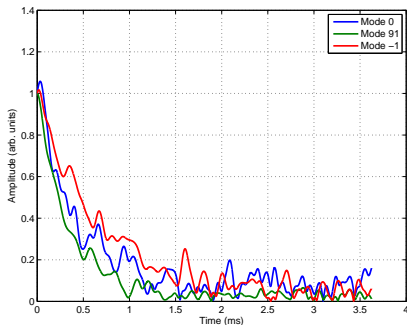
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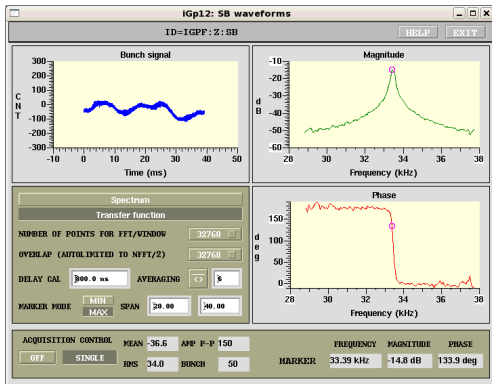
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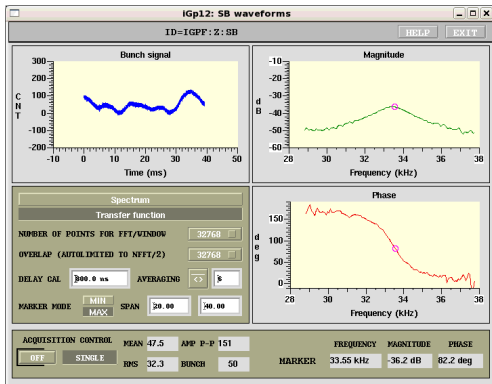
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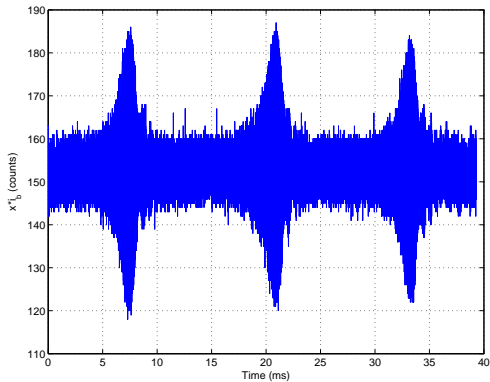
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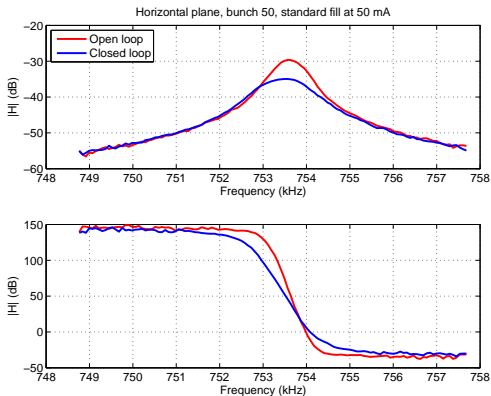
A Few Examples from TLS



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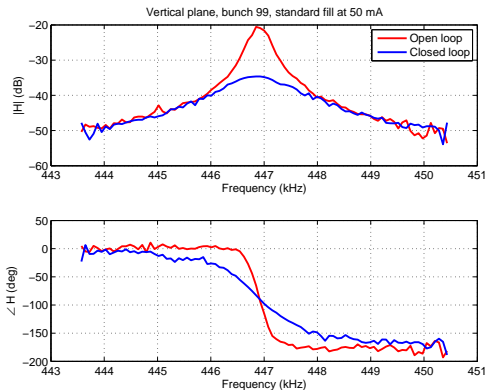


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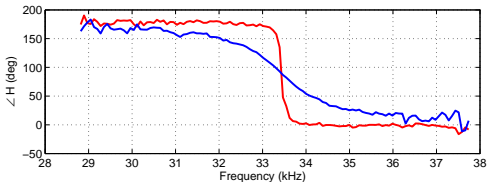
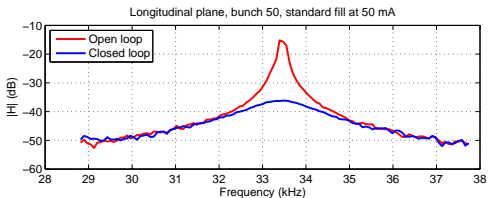
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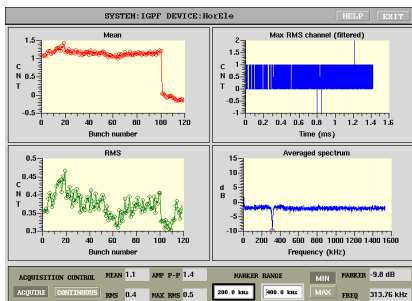
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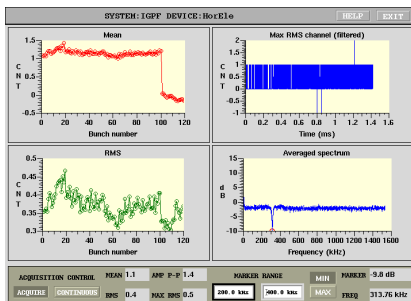


Parasitic Tune Measurement



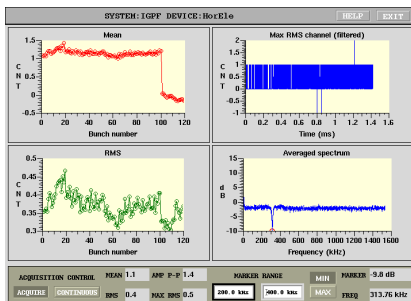
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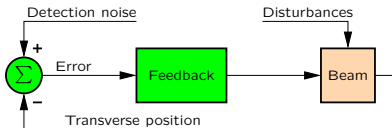
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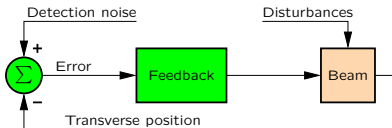
Why Is There a Notch?



- Beam response is resonant at the tune frequency;
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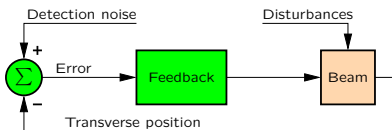
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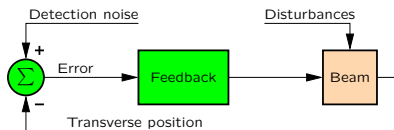
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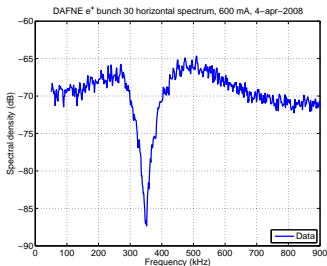


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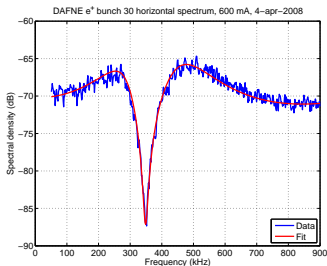
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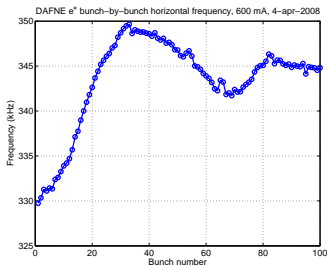
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- **Completely parasitic** measurement of bunch-by-bunch tunes.

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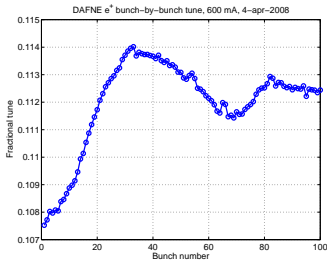
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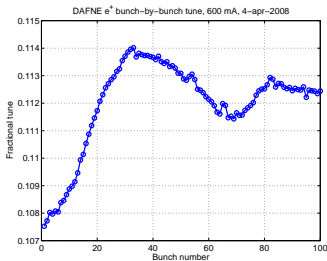


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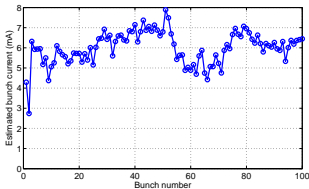
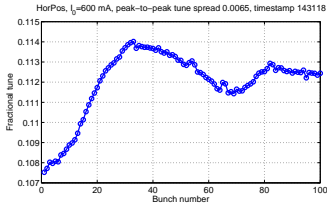
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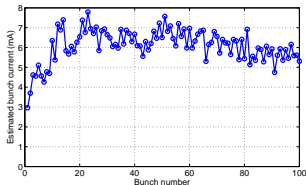
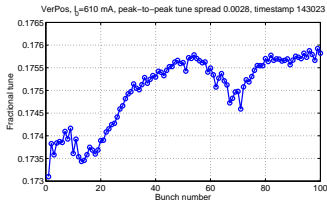
DAΦNE: Horizontal vs. Vertical



- Two measurements at 420 mA;
- Horizontal tune spread is 6.5×10^{-3} ;
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- Horizontal plane shows evidence of strong electron-cloud instabilities.

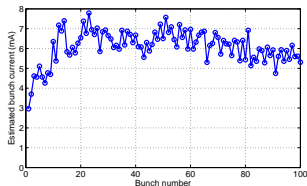
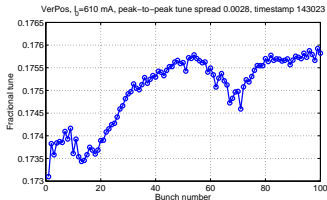


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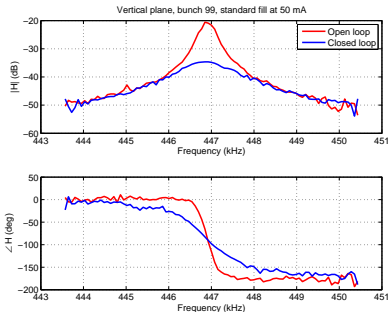
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Tune Tracker: General Approach

- Turn off feedback for one selected bunch;
- Apply low amplitude sinusoidal excitation to that bunch;
- Measure the response and extract phase shift between excitation and response;
- Adjust excitation frequency to keep the phase shift constant;
- At some value of the phase shift we will excite the beam on resonance;
- If the tune changes, closed-loop tune tracker follows;
- Tune tracking can be slow (1-10 Hz) or fast (kHz).

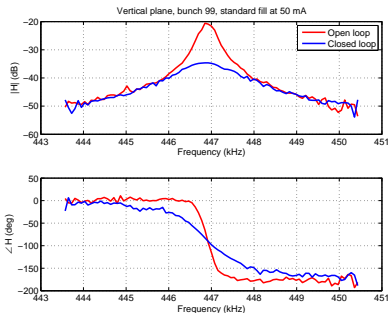


Beam Transfer Function and Tracking



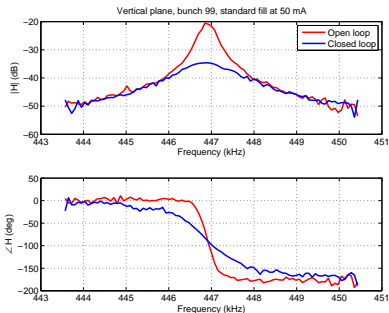
- Open loop response has steep phase slope;
- At -90 degrees phase shift excitation is on resonance;
- Negative phase slope — negative phase tracker gain.

Beam Transfer Function and Tracking



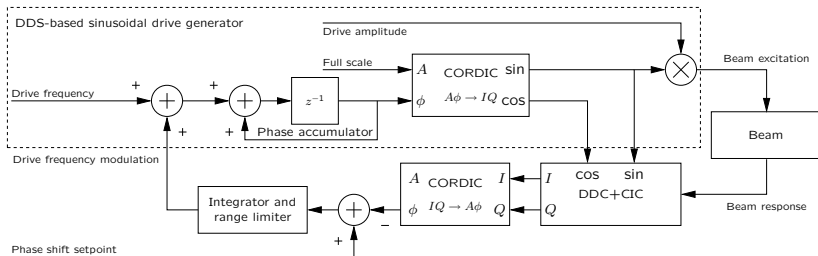
- Open loop response has steep phase slope;
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Beam Transfer Function and Tracking

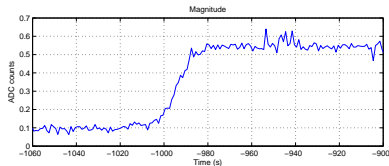
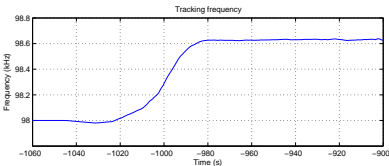
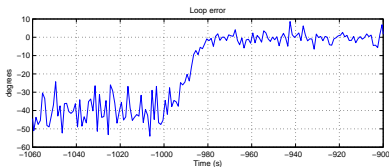


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Tune Tracker: Block Diagram



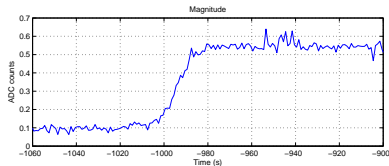
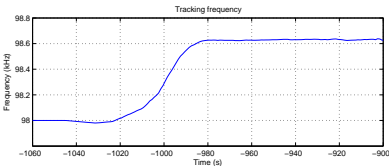
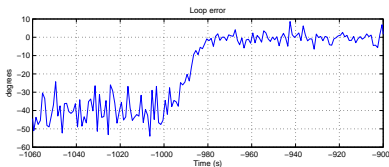
Slow Tune Tracking in NSLS-II



- Tune tracking loop closed around -1000 seconds;
- Low gain — slow settling;
- Once settled, the loop maintains stable oscillation amplitude by tracking the variations in the tune.



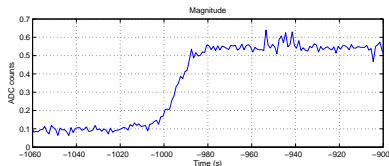
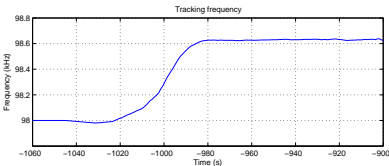
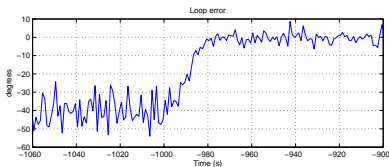
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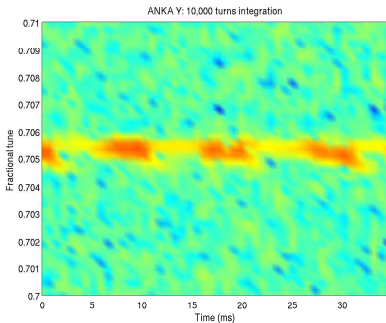
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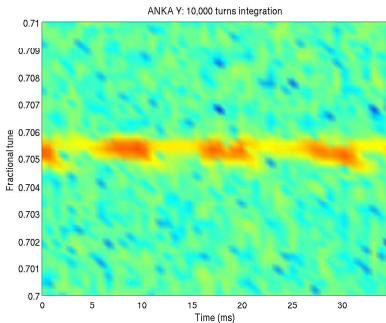


Slow Tune Tracking in ANKA



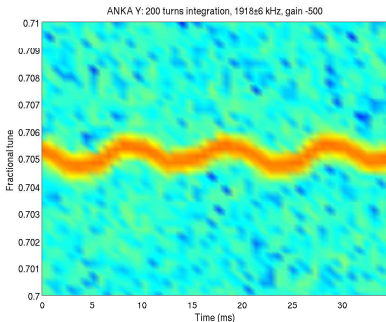
- Slow tracking — 10^4 turns integration, 120 Hz measurement bandwidth;
- Spectrogram of the bunch under tracking control;
- Suggestive of periodic tune variation.

Slow Tune Tracking in ANKA



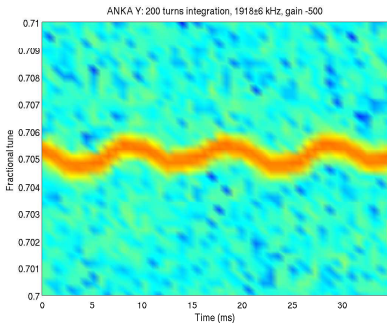
- Slow tracking — 10^4 turns integration, 120 Hz measurement bandwidth;
- Spectrogram of the bunch under tracking control;
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Fast Tune Tracking in ANKA



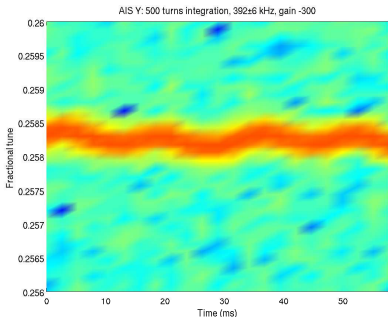
- Fast tracking — 200 turns integration, 6 kHz measurement bandwidth;
- Spectrogram of the bunch under tracking control;
- 100 Hz tune variation (quadrupole supply ripple).

Fast Tune Tracking in ANKA



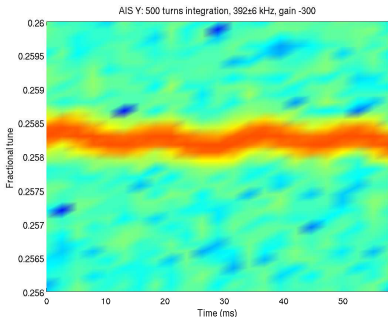
- Fast tracking — 200 turns integration, 6 kHz measurement bandwidth;
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Fast Tune Tracking in the ALS



- Fast tracking — 500 turns integration, 1.3 kHz measurement bandwidth;
- Spectrogram of the bunch under tracking control;
- 60 Hz tune variation.

Fast Tune Tracking in the ALS



- Fast tracking — 500 turns integration, 1.3 kHz measurement bandwidth;
- Spectrogram of the bunch under tracking control;
- 60 Hz tune variation.

Summary

- Modern bunch-by-bunch feedback system is capable of much more than just keeping the beam stable;
- Programmable hardware enables a number of experimental techniques for controlling bunch positions and currents;
- Modern feedback systems provide multiple ways of monitoring beam dynamics in real time.



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