#### Advanced Signal Processing for APS-U

#### D. Teytelman

Dimtel, Inc., San Jose, CA, USA

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ASP for APS-U

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- Horizontal difference signal derived from four buttons;
- At zero offset amplitude goes to zero;
- Replicate the pulse two or more times;
- Spaced by detection frequency period;
- For analysis can replace the complex shape with a sinusoidal burst at Mω<sub>rf</sub>;
- Detected signal after filtering.





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# **Energy Sensing Analysis**



- Conventional front-end with  $\Delta X$  input;
- Model signal at detection frequency as  $v(t) = A(x_0 + \Delta x) \sin(M\omega_{rf}(t + \tau));$

| Parameter             | Definition                             |
|-----------------------|--|
| <i>x</i> <sub>0</sub> | Orbit offset                           |
| $\Delta x$            | Horizontal oscillation $D\epsilon/E_0$ |
| Μ                     | Detection harmonic                     |
| au                    | Time oscillation                       |
|                       |  |



- Assume energy oscillation  $\epsilon = \epsilon_0 \cos \omega_s t$ ;
- Dispersion term is  $\Delta x = D\epsilon_0/E_0 \cos \omega_s t$ ;
- Time domain oscillation is  $\tau = \frac{\alpha \epsilon_0}{E_0 \omega_s} \sin \omega_s t$ ;
- Pickup gain factor A = Q<sub>b</sub>g<sub>0</sub>M, assuming relatively low RF harmonics;
- Mixing v(t) with cos Mω<sub>rf</sub>t and sin Mω<sub>rf</sub>t for phase/amplitude detection respectively;
- Amplitude signal, after low-pass filtering is  $A/2(x_0 + \Delta x) \cos M\omega_{\rm rf}\tau$ ;
- Further downconvert baseband output of the amplitude detector relative to synchrotron reference to extract phase shift.



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#### • 352 MHz;

- 704 MHz;
- 1056 MHz;
- 1408 MHz;
- 1760 MHz;

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 Linear scaling for amplitude, quadratic for phase, just as expected.



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ASP for APS-U



- Original oscillation and detected signal;
- Nearly perfect at RF;
- Deviations from original at
- Larger effect at the third
- And fourth:
- As well as fifth:
- Generating odd harmonics,

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- Original oscillation and detected signal;
- Nearly perfect at RF;
- Deviations from original at peak phase excursions;
- Larger effect at the third harmonic:
- And fourth:
- As well as fifth:
- Generating odd harmonics, can be harmful with wide tune spreads.



#### 80 μm offset;

- 352 MHz;
- 704 MHz;
- 1056 MHz;
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80 μm offset;
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- 1408 MHz.



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- 352 MHz;
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- 1056 MHz;
- 1408 MHz.





- 320 µm offset;
- 352 MHz;
- 704 MHz;
- 1056 MHz;
- 1408 MHz;
- Very high distortion.

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- 320 μm offset;
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# • A 1296 tap FIR filter acting on consecutive buckets;

- Signal for the turn-by-turn feedback filter is current bunch signal minus the average over the full turn;
- High rejection of low frequencies, close to unity gain by the first revolution harmonic;
- Gain is nearly perfect near revolution harmonics;
- Ripple between revolution harmonics should not be a problem;

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• Efficient CIC implementation.



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- A 1296 tap FIR filter acting on consecutive buckets;
- Signal for the turn-by-turn feedback filter is current bunch signal minus the average over the full turn;
- High rejection of low frequencies, close to unity gain by the first revolution harmonic;
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- 32-tap FIR, downsampling of 3 can run in current iGp12 without any modifications;
- Simple-minded design 6 tap averager to reject horizontal motion;
- Use remaining 26 taps to achieve DC rejection;
- Notch around horizontal frequency (45 kHz);
- Peak gain and nearly zero phase shift at 2.2 kHz;

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- 32-tap FIR, downsampling of 3 can run in current iGp12 without any modifications;
- Simple-minded design 6 tap averager to reject horizontal motion;
- Use remaining 26 taps to achieve DC rejection;
- Notch around horizontal frequency (45 kHz);
- Peak gain and nearly zero phase shift at 2.2 kHz;
- Not optimal, just a rough idea.



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- Need to keep physical and electronic offsets small;
- Detection at 704 MHz is probably a good idea;
- Mode 0 response can, in principle, be filtered out in the feedback FPGA;
- Can use iGp12 to test dispersive feedback in the APS.



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