

Dimtel Digital Low-level RF

LLRF9 For SPEAR3

D. Teytelman

Dimtel, Inc., San Jose, CA, USA

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Overview

- LLRF9 Introduction
- Inputs and Interlocks
- Feedback Loops
- Diagnostics

Proposed Architecture

- Overall Topology
- Issues Needing Clarification

LLRF Characterization

- Frequency Domain
- Time Domain

Stability Measurements and Precision Calibration

- Thermal
- Tuning Scans
- Beam-Based Calibration

Outline

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LLRF9 System

LLRF9



- ▶ A single 2U chassis;
- ▶ 9 input RF channels;
- ▶ 2 output RF channels:
 - ▶ Amplified;
 - ▶ Filtered;
 - ▶ Interlocked.
- ▶ Two spare outputs.
- ▶ Tuner motor control;
- ▶ External interlock daisy-chain;
- ▶ Two external trigger inputs;
- ▶ Eight opto-isolated baseband ADC channels.

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Machines

Ring	Stations	Cavities
ELSA	1	2
KARA	2	4
KARA booster	1	1
SESAME	4	4
SESAME booster	1	1
DELTA	2	2
Diamond booster (demo)	1	1
LNLS (demo)	2	2
LNLS booster (demo)	1	1

- ▶ System is in daily operation at 4 storage rings and 2 boosters;
- ▶ Successfully demonstrated at 3 other rings;
- ▶ Power sources — klystrons, SSAs, IOTs.



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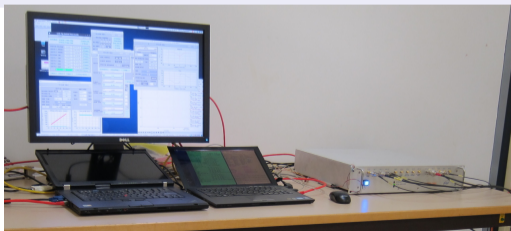
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ID=LLRF:BRD1					HELP	EXIT
INTERLOCKS						
EXTERNAL INTERLOCK INPUT	ENABLE			MASK		
AMPLITUDE	340.74 kv	305.41 kv	625.42 kv			
THRESHOLD	380.00 kv	340.00 kv	780.00 kv			
RAW AMPLITUDE	6364.5 counts	5952.3 counts	6207.6 counts	6098.0 counts		
RAW THRESHOLD	7098	6627	6932	8191		
EXTERNAL	CHANNEL 0	CHANNEL 1	CHANNEL 2	CHANNEL 3		
RESET	RESET	RESET	RESET	RESET		
5782454	36046144	36067981	92105109			
TRIP CAPTURE	7122	6671	6957			
TRIP VALUE	381.30 kv	342.26 kv	785.54 kv			

- ▶ Fast interlock threshold can be set for each of 9 RF inputs;
- ▶ Guaranteed trip in 11 ADC clock cycles (100 ns);
- ▶ Multiple layers of interlock protection for drive outputs. On interlock trip:
 - ▶ Hardware controlled RF switch is opened;
 - ▶ FPGA DAC drive is set to zero;
 - ▶ DAC is disabled (hardware powerdown);
 - ▶ DDR output flip-flop is held reset.

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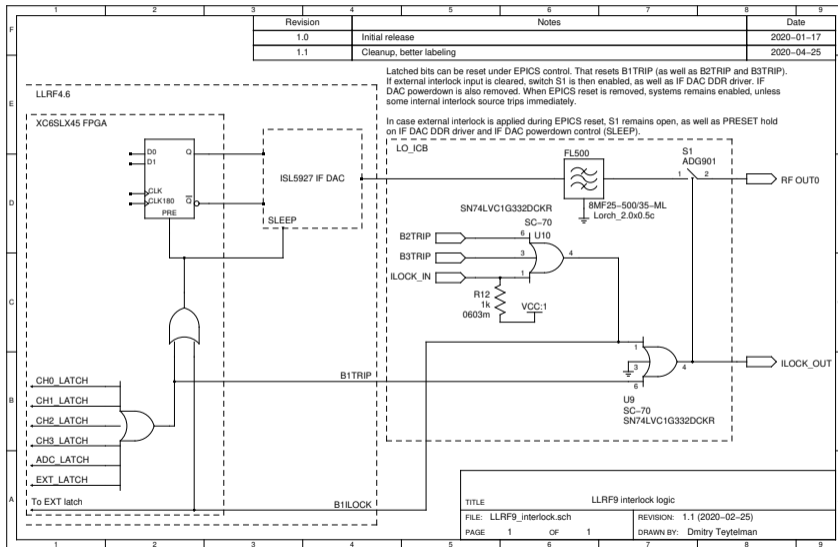
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Interlock Output Path

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Interlock Chain - Continued



LLRF HELP EXIT

INTERLOCK STATUS RESET

TRIP SOURCE	TIME
CAVITY 1 PROBE1	0.000 us
CAVITY 2 PROBE1	384.022 us

Board 1 interlock Board 2 interlock Board 3 interlock

- ▶ External interlock enable input and interlock output allow for easy daisy-chaining:
 - ▶ Opto-isolated input;
 - ▶ 5 volt logic and solid-state relay output.
- ▶ Spare output used in some machines as HVPS enable/interlock;
- ▶ All interlock sources are timestamped;
- ▶ IOC automatically sorts events to simplify trip diagnostics.

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Tuner Loop

LLRF:TUNER:C1

TUNER LOOP

LOOP CONTROL

PROP	INT	DIFF	ANTI WINDUP
<input type="text" value="5.0"/>	<input type="text" value="1.5"/>	<input type="text" value="0.0"/>	<input type="text" value="-0.1"/>

DEADBAND

MINIMUM FORWARD POWER

LOAD ANGLE OFFSET

LOOP SIGN ERROR

Tuner 1 Motor Control

Tuner 2 Motor Control

Probe balancing loop

- ▶ Loop runs in the EPICS IOC at 10 Hz;
- ▶ Keeps cavity forward and probe phases aligned;
- ▶ Options for one or two motors per cavity, field balancing loop for multi-cell cavities;
- ▶ Adjustable deadband to avoid unnecessary mechanical wear.

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The screenshot shows a control window titled "ID=LLE1: C1T1" with "HELP" and "EXIT" buttons. The main area is titled "GALIL DMC-21X3 STREAM DEVICE" and displays the following data:

VELOCITY COMMAND	0.000 deg/s
ENCODER POSITION	315691.920 deg
ENCODER VELOCITY	0.000 deg/s
ANALOG INPUT	-5.549 V

Below the data, there are status indicators for MOVING (green circle), ENABLE (red circle), DIR (CW), CCW LIM (green circle), and CW LIM (green circle). At the bottom, there are "DISABLE" and "ENABLE" buttons, and a "STATUS" field showing "0x6D".

- ▶ LLRF9 supports a number of off-the-shelf motor controllers:
 - ▶ Galil DMC-21X3 stepper/brushed DC/brushless;
 - ▶ Schneider Electric Motion Mdrive Plus stepper;
 - ▶ Aerotech Soloist brushed DC.
- ▶ Interfaces include Ethernet, RS-485, RS-422;
- ▶ Plunger position monitoring from analog potentiometer;
- ▶ Standard support for limit switches;
- ▶ EPICS MotorRecord is supported, not recommended.

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The screenshot shows a terminal window titled "ID=LLE1: C1T1" with "HELP" and "EXIT" buttons. The main content is a "GALIL DMC-21X3 STREAM DEVICE" control panel. It features several data fields: "VELOCITY COMMAND" set to "0.000 deg/s", "ENCODER POSITION" at "315691.920 deg", "ENCODER VELOCITY" at "0.000 deg/s", and "ANALOG INPUT" at "-5.549 V". Below these are status indicators for "MOVING" (green circle), "ENABLE" (red circle), "DIR" (labeled "CW" with a green circle), and "CW LIM" (green circle). At the bottom, there are "DISABLE" and "ENABLE" buttons, a "STATUS" field showing "0x6D", and a "0x6D" value field.

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The screenshot shows a control interface for a Galil DMC-21X3 stream device. At the top, it displays 'ID=LLE1:C1T1' and has 'HELP' and 'EXIT' buttons. The main area is titled 'GALIL DMC-21X3 STREAM DEVICE' and contains several data fields and controls:

- VELOCITY COMMAND:** A text input field containing '0.000 deg/s'.
- ENCODER POSITION:** A read-only field showing '315691.920 deg'.
- ENCODER VELOCITY:** A read-only field showing '0.000 deg/s'.
- ANALOG INPUT:** A read-only field showing '-5.549 V'.
- Moving Status:** A row of five indicators: 'MOVING' (green circle), 'ENABLE' (red circle), 'DIR' (text), 'CCW LIM' (green circle), and 'CW LIM' (green circle).
- Buttons:** 'DISABLE' and 'ENABLE' buttons are located below the status indicators.
- STATUS:** A read-only field at the bottom right showing '0x6D'.

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- VELOCITY COMMAND: 0.000 deg/s
- ENCODER POSITION: 315691.920 deg
- ENCODER VELOCITY: 0.000 deg/s
- ANALOG INPUT: -5.549 V
- Moving status: A green circle indicates the motor is moving.
- ENABLE status: A red circle indicates the motor is not enabled.
- DIR: CW
- CCW LIM: A green circle indicates the counter-clockwise limit is active.
- CW LIM: A green circle indicates the clockwise limit is active.
- Buttons: "DISABLE" and "ENABLE" buttons are present.
- STATUS: 0x6D

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The screenshot shows a window titled "ID=LLRF: C1T1" with "HELP" and "EXIT" buttons. The main area is titled "MOTOR RECORD" and contains the following data:

POSITION (DEG)	6607.06
RELATIVE VALUE (DEG)	0.00
VELOCITY (DEG/S)	5000.00
ACCELERATION TIME (S)	0.040
DIRECTION OF TRAVEL	0
RAW MOTOR POSITION	-939567
READBACK VALUE (DEG)	-6606.33047
ANALOG INPUT	986

At the bottom, there are status indicators: "DONE" (red dot), "MOVING" (green dot), "LOW LIM" (green dot), and "HI LIM" (green dot).

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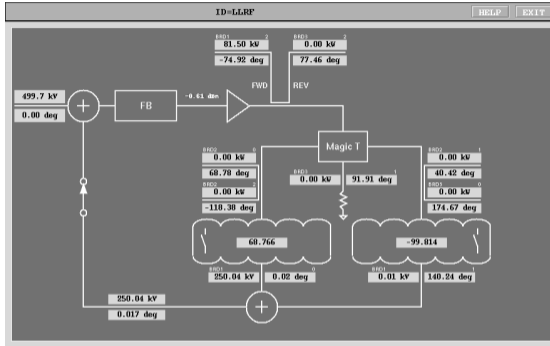
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Top Level Panel: ANKA



▶ Two cavity station (ANKA):

- ▶ 6 cavity signals;
- ▶ Klystron forward and reflected;
- ▶ Magic T load.

- ▶ Two tuner loops;
- ▶ Active blocks for quick control panel access.

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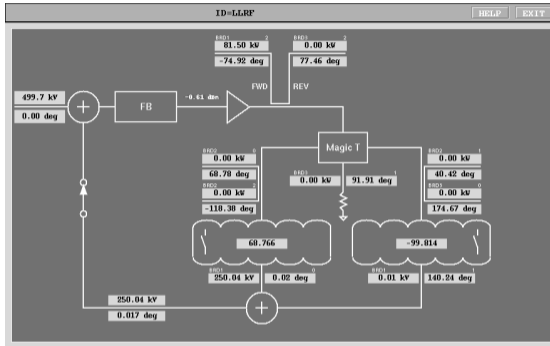
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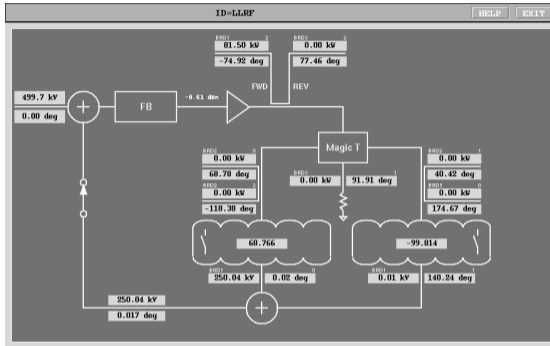
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Top Level Panel: ANKA



▶ Two cavity station (ANKA):

- ▶ 6 cavity signals;
- ▶ Klystron forward and reflected;
- ▶ Magic T load.

- ▶ Two tuner loops;
- ▶ Active blocks for quick control panel access.

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LLRF : STATE : C1		
	<input type="button" value="HELP"/>	<input type="button" value="EXIT"/>
STATE MACHINE CONTROL		
TIMEOUT	<input type="text" value="120.0 seconds"/>	
MAXIMUM TUNING ERROR	<input type="text" value="5.0 degrees"/>	
OPEN LOOP TUNING	<input type="text" value="60.0 kv"/>	
OPERATING VOLTAGE	<input type="text" value="600.0 kv"/>	
DUMP WINDOW TOP	<input type="text" value="110.0 kv"/>	
DUMP WINDOW BOTTOM	<input type="text" value="100.0 kv"/>	
DUMP RATE, PER SECOND	<input type="text" value="0.2500 kv"/>	

- ▶ Simplified controls: ON and OFF;
- ▶ State machine handles station turn on
 - ▶ Cavity tuning in open loop state;
 - ▶ Feedback loop closure;
 - ▶ Ramping to nominal field;
 - ▶ Rampdown and turn-off.
- ▶ Monitors error conditions (interlocks) and timeouts.

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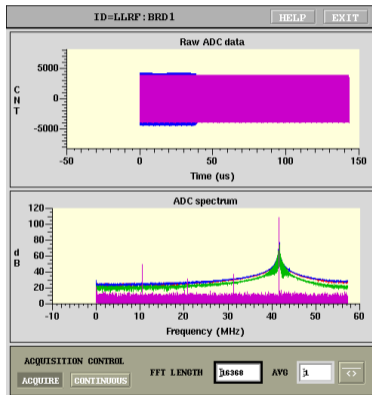
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ADC Waveform Capture

LLRF9



- ▶ 12 ADC channels sampling IF signals (9 inputs, 3 references);
- ▶ 24576 sample buffer;
- ▶ 10 updates per second in free running mode;
- ▶ Multiple hardware trigger sources:
 - ▶ External trigger;
 - ▶ Ramp profile start;
 - ▶ Interlock;
 - ▶ Feedback loop closure.
- ▶ Supports pre-trigger acquisition for trip capture.

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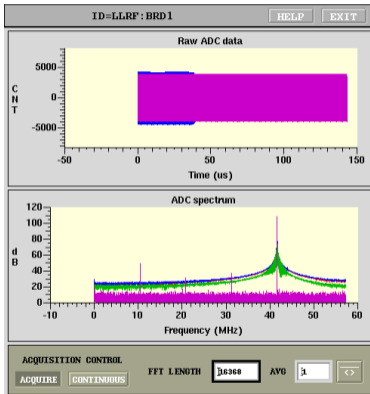
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ACQUISITION CONTROLS			
POST-TRIGGER LENGTH	<input type="text" value="16384"/>		
CH2/CH3 WAVEFORM	ADC2/ADC3 <input type="checkbox"/>		
TRIGGER SELECT	SOFTWARE		
	HARDWARE		
HARDWARE TRIGGER	RAMP <input type="checkbox"/>		

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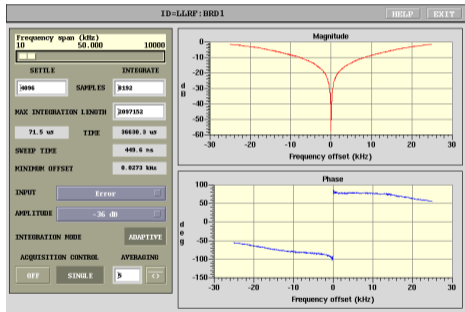
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- ▶ High resolution (1024 point) swept analyzer;
- ▶ Adjustable excitation level;
- ▶ Fast sweep times with proprietary carrier suppression algorithm;
- ▶ Multiple probe points within the system:
 - ▶ Cavity probe;
 - ▶ Cavity sum;
 - ▶ Error signal;
 - ▶ Drive output.
- ▶ Spectrum analyzer mode with excitation disabled.

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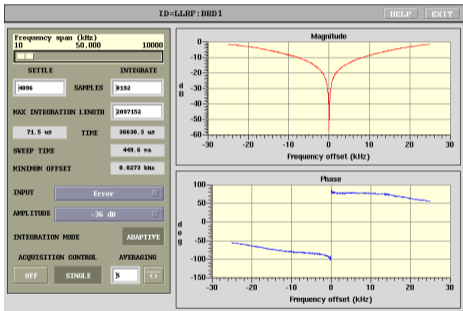
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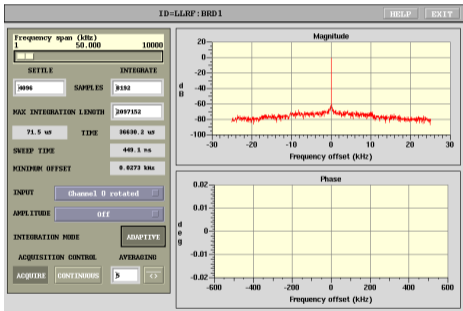
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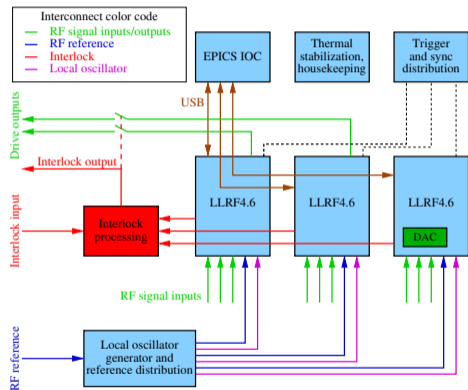
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LLRF9 Internal Layout

LLRF9



- ▶ 3 LLRF4.6 modules, each with 4 RF inputs;
- ▶ One input per module dedicated to reference monitoring;
- ▶ Identical FPGA code on all 3 modules;
- ▶ Two complete field control paths with filtering/interlocking.

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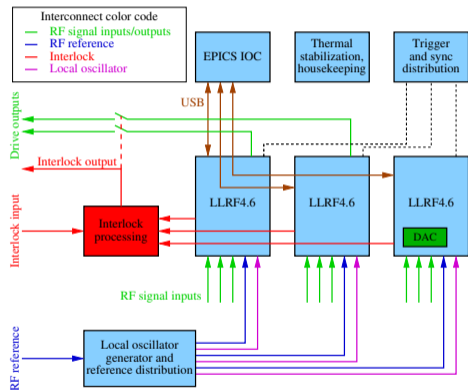
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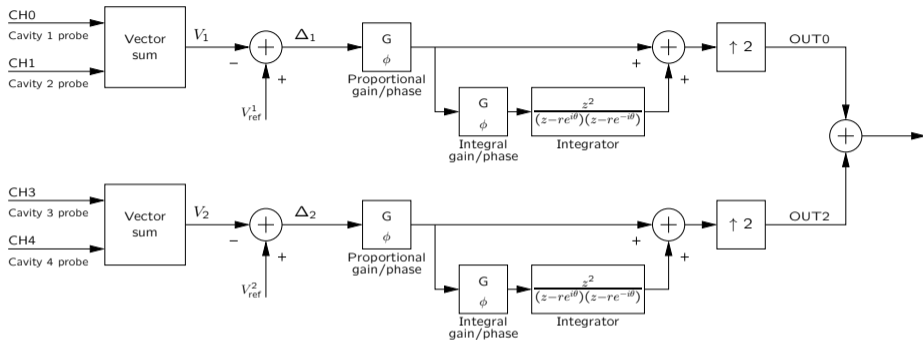
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Dual Control Loops



- ▶ Integral loops zero Δ at RF;
- ▶ Two integrators on at once — balancing problems;
- ▶ Direct loop with moderate gain is more tolerant;
- ▶ **Two direct, one integral;**
- ▶ Integral: high gain at low frequencies;
- ▶ Direct: 12–15 dB of wideband feedback for all 4 cavities.

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Interfaces to Define

- ▶ Total number of channels and channel selection;
- ▶ Tuner motor control;
- ▶ HVPS control/interlocking;
- ▶ Opto-isolated slow ADC and interlocking;
 - ▶ Each LLRF9 includes an 8 channel 12 bit opto-isolated ADC;
 - ▶ Capable of triggering interlocks (window comparator);
 - ▶ Four configurable input ranges: ± 5 V, ± 10 V, 0–5 V, 0–10 V;
 - ▶ Each channel is polled at 13.75 ksps.
- ▶ Interlock daisychain input and output;
- ▶ Digital input levels, connectors.

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Development needed

- ▶ **Configure 4 tuner loops (easy);**
- ▶ Structure to integrate monitoring information from multiple LLRF9 units;
- ▶ Top-level interlock summary processor, reset handler;
- ▶ Operating procedure for dual loop operation;
- ▶ State machine to run SPEAR3 configuration.

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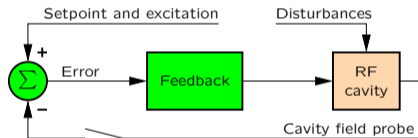
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Open Loop Transfer Function



- ▶ Measured from setpoint to the cavity probe;
- ▶ Feedback block in open loop has no dynamics, just gain and phase shift;
- ▶ Open loop cavity response;
- ▶ Fit resonator model to extract gain, loaded Q ,
- ▶ Extremely useful for configuring the feedback loops, tuner loops, general diagnostics.

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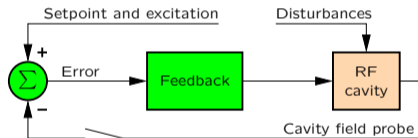
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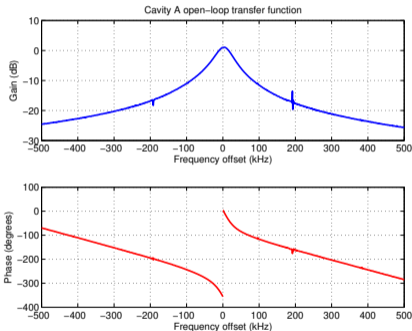
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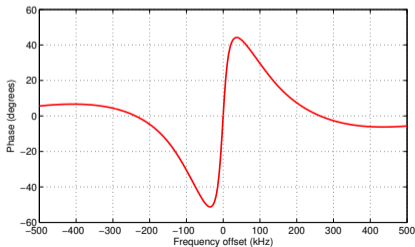
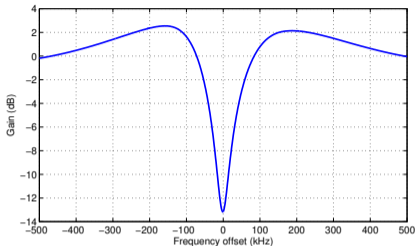
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Closed Loop Transfer Functions



- ▶ Measured from setpoint to the error signal;
- ▶ Shows attenuation at frequencies where feedback has gain;
- ▶ Perturbations at the input of the cavity are rejected with the same transfer function;
- ▶ Proportional only;
 - ▶ Proportional and integral, much higher rejection at low frequencies;
 - ▶ Easier to see with the logarithmic frequency scale.

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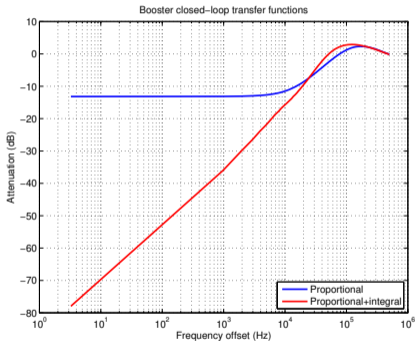
LLRF Characterization

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Closed Loop Transfer Functions



- ▶ Measured from setpoint to the error signal;
- ▶ Shows attenuation at frequencies where feedback has gain;
- ▶ Perturbations at the input of the cavity are rejected with the same transfer function;
- ▶ Proportional only;
- ▶ Proportional and integral, much higher rejection at low frequencies;
- ▶ Easier to see with the logarithmic frequency scale.

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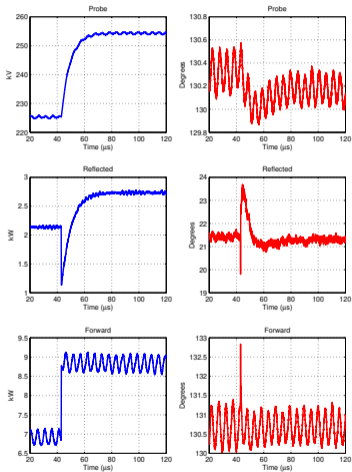
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Step Response



- ▶ Ramp start triggers waveform acquisition;
- ▶ Ramp profile loaded with a 10% amplitude step (230 to 253 kV);
- ▶ Open loop: phase shift (AM-PM in power stage), setpoint error;
- ▶ Closed loop response is much faster, as expected;
- ▶ A bit too much gain, overshoot seen;
- ▶ Prominent ripple due to SSA power supply switching at 190 kHz.

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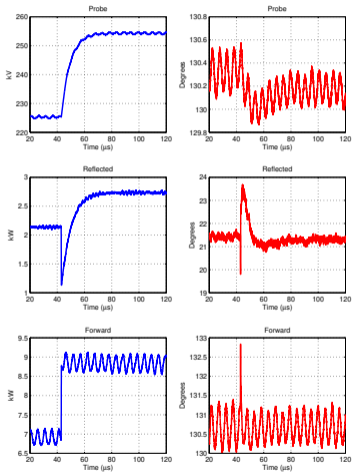
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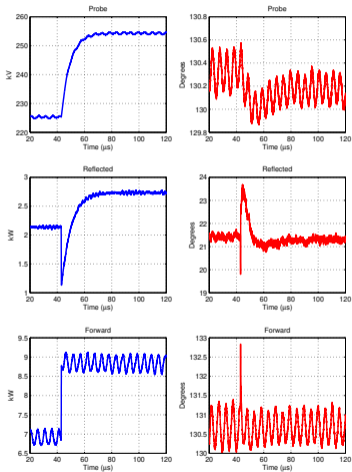
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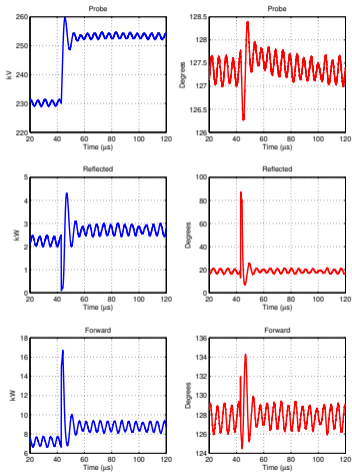
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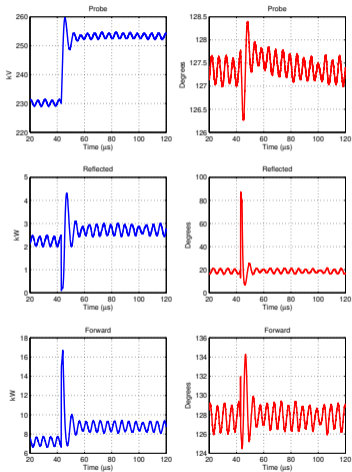
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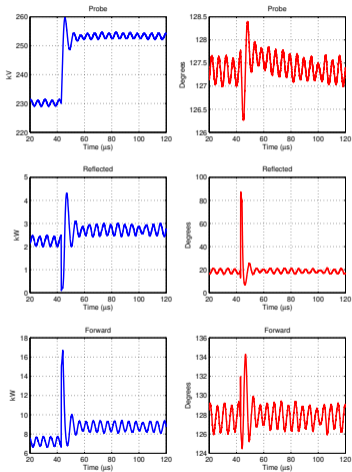
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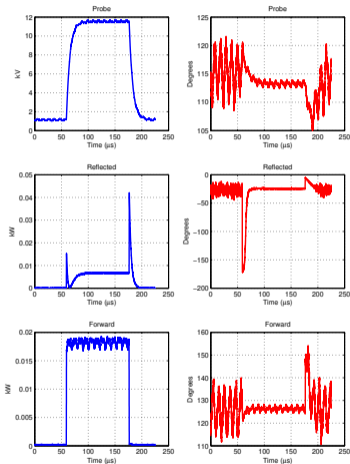
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Pulse Response



- ▶ Open-loop pulse response, cavity A;
- ▶ Base 2 kV, pulse 20 kV;
- ▶ Larger reflected power peak at the falling edge, expected for coupling factor $\beta > 1$;
- ▶ Phase slope during pulse decay indicates the cavity is slightly detuned.

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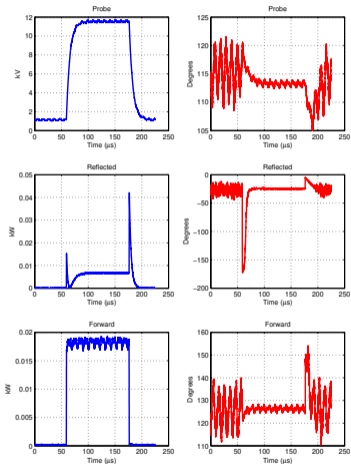
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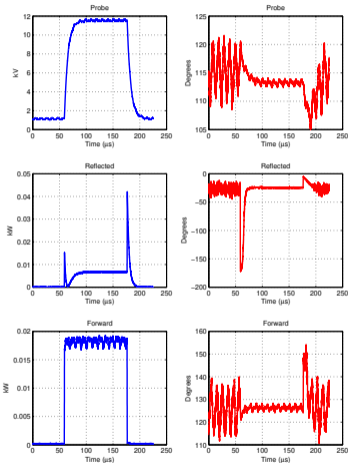
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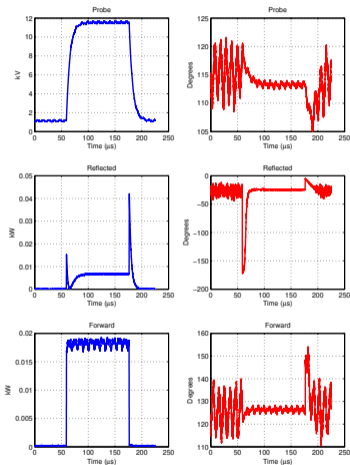
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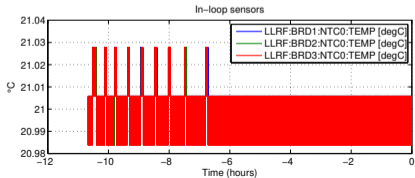
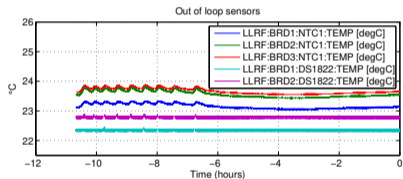
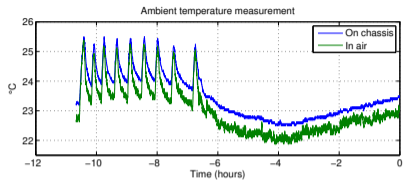
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Thermal Stability: Lab Measurements



- ▶ 9 internal sensors on cold plate: 6 NTCs, 3 DS18B20 digital sensors;
- ▶ Three temperature stabilization loops using thermoelectric coolers;
- ▶ Two external sensors, in air and attached to chassis;
- ▶ Tight stabilization of in-loop sensors;
- ▶ Residual sensitivity of out-of-loop sensors is $0.09\text{--}0.12\text{ }^{\circ}\text{C}/^{\circ}\text{C}$.

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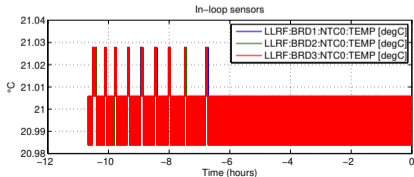
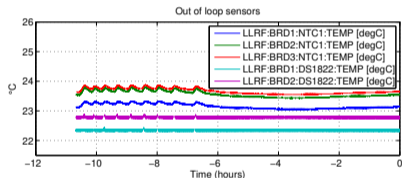
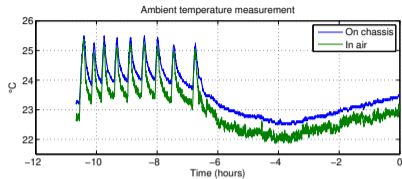
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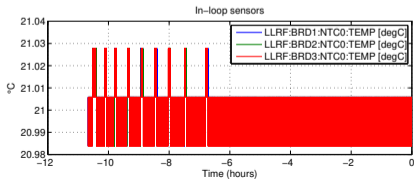
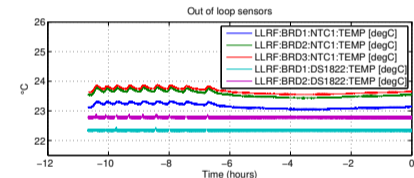
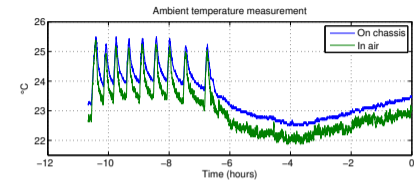
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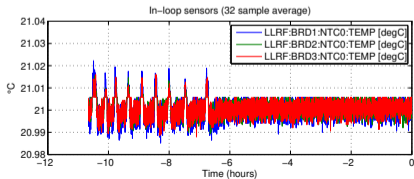
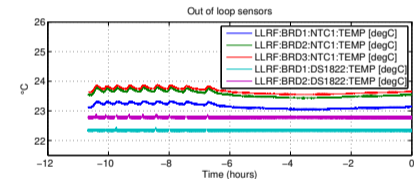
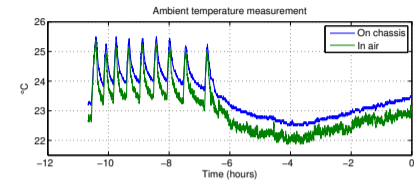
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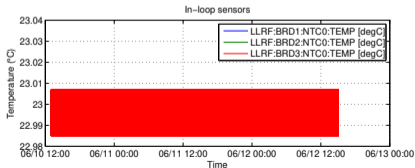
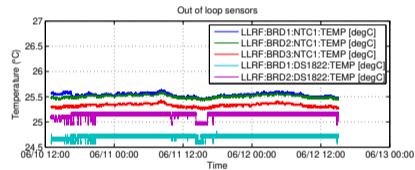
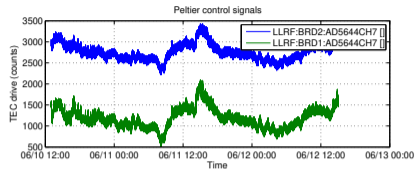
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Thermal Stability: LNLs Measurements



- ▶ Recorded over 2 days;
- ▶ Diurnal temperature variation clearly seen in out of loop sensors and Peltier control signals;
- ▶ Out of loop NTC sensors show $0.22\text{ }^{\circ}\text{C}$ peak-to-peak variation.

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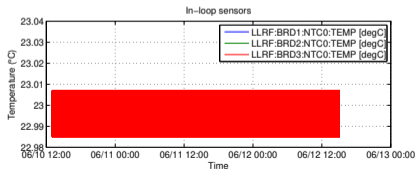
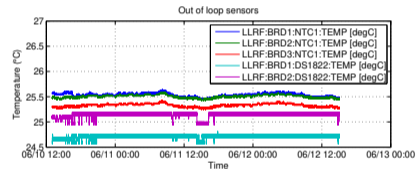
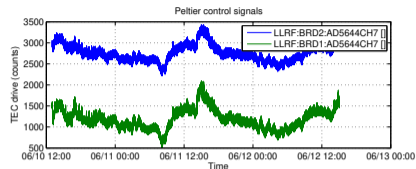
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Thermal Stability: LNL5 Measurements



- ▶ Recorded over 2 days;
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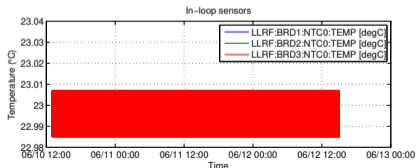
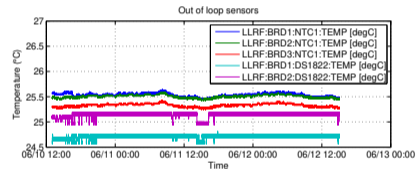
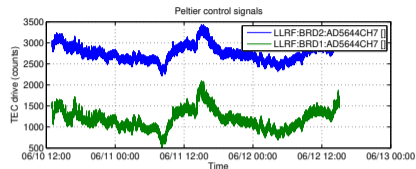
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Tuning Scan at SESAME

LLRF9

- ▶ Run the station in open loop, fixed setpoint;
- ▶ Move the cavity from limit switch to limit switch;
- ▶ At multiple points record:
 - ▶ Probe voltage and phase;
 - ▶ Forward and reflected power and phase;
 - ▶ LLRF9 output power meter;
 - ▶ Tuner potentiometer;
 - ▶ **Open-loop transfer function.**
- ▶ A lot of interesting plots!

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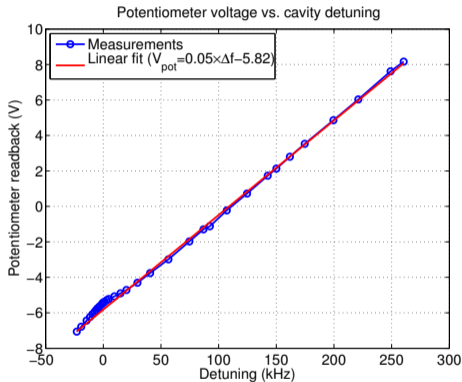
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Tuner Position Potentiometer vs. Detuning



- ▶ Nearly linear;
- ▶ A deviation near zero detuning is caused by wall heating;
- ▶ Slope should be consistent, offset shifts with temperature.

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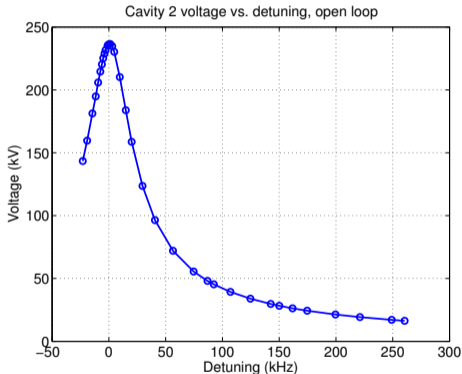
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Cavity Voltage vs. Detuning



- ▶ Cavity voltage peaks around 0;
- ▶ Zooming in we see an interesting effect — peak voltage is around 650 Hz;
- ▶ Likely due to imperfect match at the SSA output.

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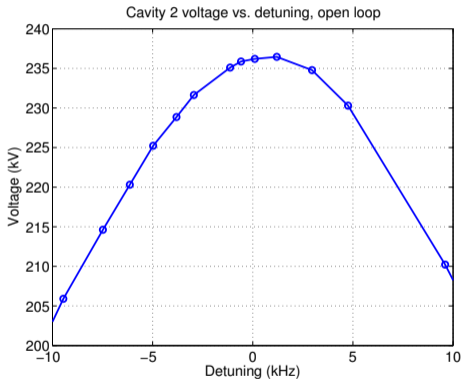
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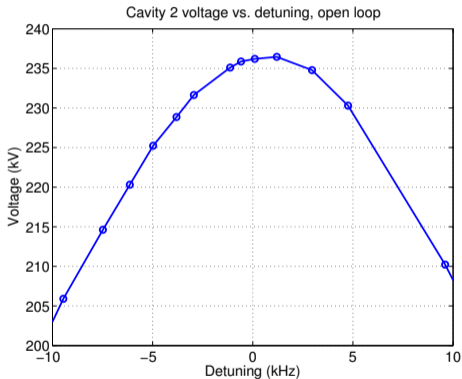
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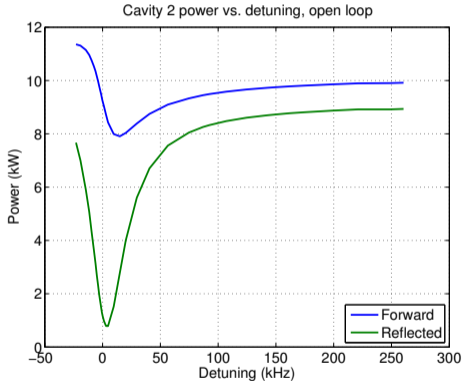
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Waveguide Power vs. Detuning



- ▶ Reflected power minimum near 0;
- ▶ Forward power reading changes due to finite directivity of couplers;
- ▶ Drive level is constant;
- ▶ Peak field and minimum reflected are offset;
- ▶ Offset minimum of reflected power is expected, directivity again.

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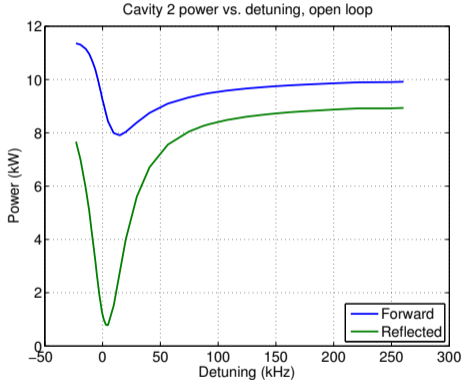
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Waveguide Power vs. Detuning



- ▶ Reflected power minimum near 0;
- ▶ Forward power reading changes due to finite directivity of couplers;
- ▶ Drive level is constant;
- ▶ Peak field and minimum reflected are offset;
- ▶ Offset minimum of reflected power is expected, directivity again.

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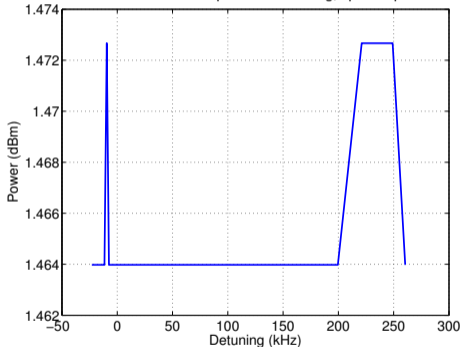
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Waveguide Power vs. Detuning

LLRF9/500 drive power vs. detuning, open loop



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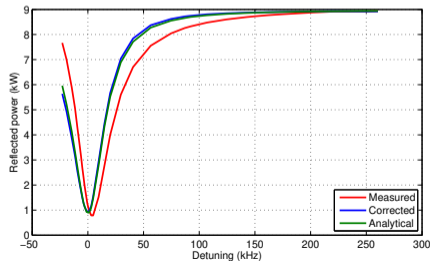
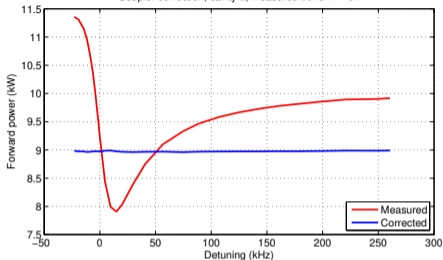
Thermal

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Coupler Directivity Correction

Coupler correction, cavity 2, measured 2016-11-07



- ▶ Assuming power source is matched, we compute the coupler directivity correction matrix;
- ▶ At each point, we compute the expected reflection coefficient at RF from cavity transfer function fit;
- ▶ Matrix elements are then adjusted to:
 - ▶ Remove variation in forward power;
 - ▶ Match measured and computed reflection.

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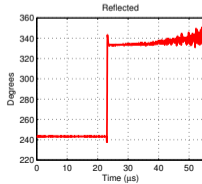
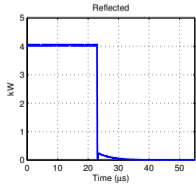
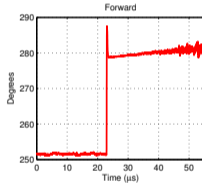
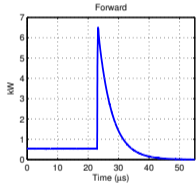
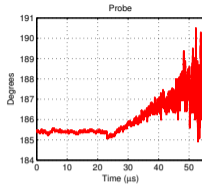
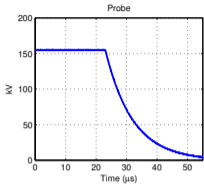
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Time Domain Cavity Response



- ▶ Step drive to 0;
- ▶ Natural cavity response;
- ▶ Can extract quality factor and detuning;
- ▶ At the same tuning point collected 20 transfer function measurements;
- ▶ Roughly 300 Hz offset between frequency and time domain.

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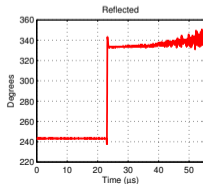
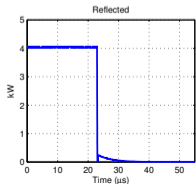
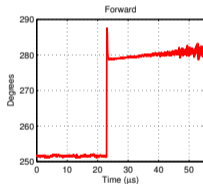
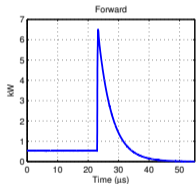
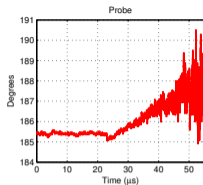
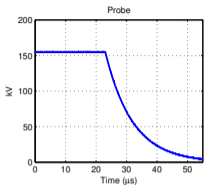
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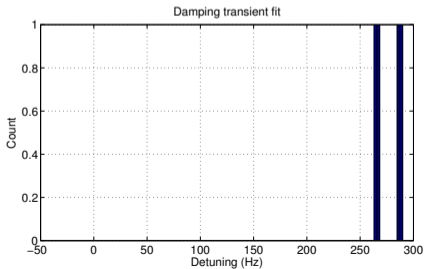
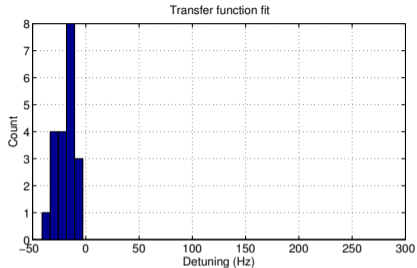
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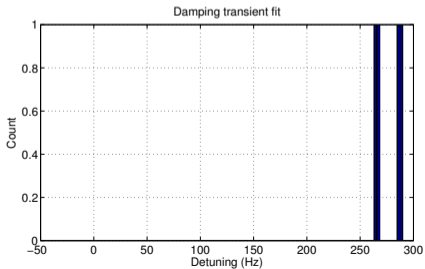
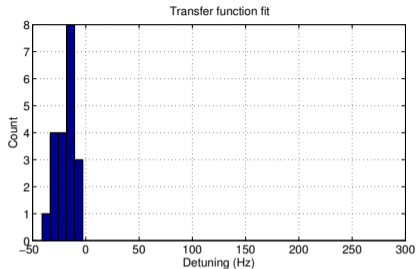
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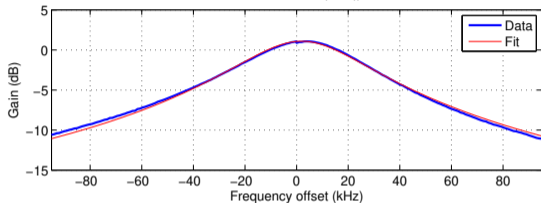
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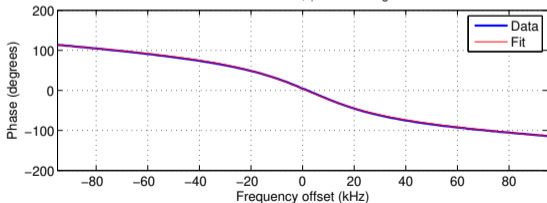
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Cavity Parameters at LNL5

Gain = 1.1, $Q = 9650.05$, $(\omega_r - \omega_{rf}) = 1.90$ kHz



$\tau = 1118.41$ ns, $\phi = 359.5$ deg



Cavity 1

Q_0 40000

Q_I 9650.0

β 3.1415

Cavity 2

Q_0 43000

Q_I 10683.4

β 3.0249

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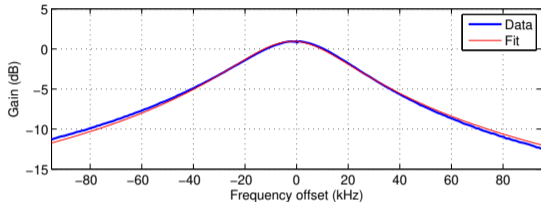
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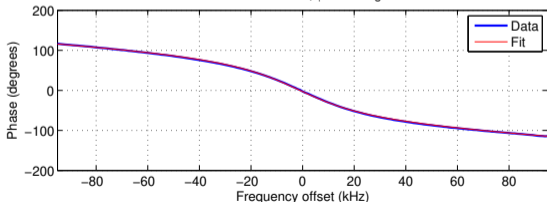
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Cavity Parameters at LNL5

Gain = 1.1, $Q = 10683.4$, $(\omega_r - \omega_{it}) = -1.51$ kHz



$\tau = 1123.44$ ns, $\phi = 0.9$ deg



Cavity 1

$$Q_0 \quad 40000$$

$$Q_I \quad 9650.0$$

$$\beta \quad 3.1415$$

Cavity 2

$$Q_0 \quad 43000$$

$$Q_I \quad 10683.4$$

$$\beta \quad 3.0249$$

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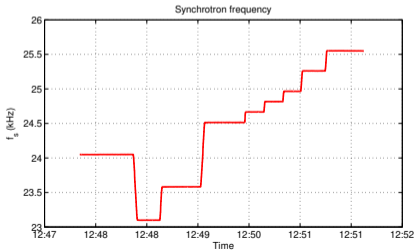
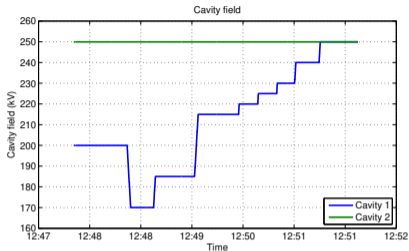
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Probe Calibration



- ▶ Scanned cavity 1 field down to 170 kV, captured synchrotron tune using LFB tune tracking;
- ▶ Fit ω_s to total voltage V_g assuming:
 - ▶ Stations are in phase (phased earlier to maximize ω_s);
 - ▶ Momentum compaction, beam energy, energy loss per turn are as published.
- ▶ Obtain scaling factors for existing calibrations.

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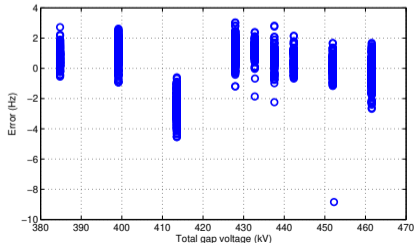
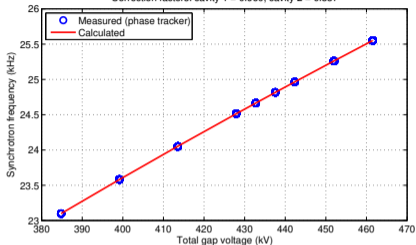
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Correction factors: cavity 1 = 0.960, cavity 2 = 0.887



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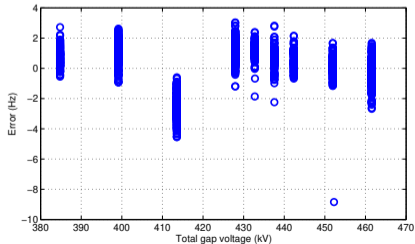
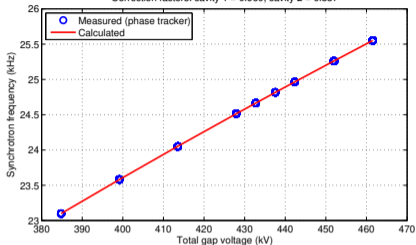
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- ▶ **LLRF9 integrates a lot of functionality in a single unit;**
- ▶ Used with normal conducting cavities at a number of machines;
- ▶ Powerful diagnostic features to simplify tuning and operation;
- ▶ Enables precision measurements of accelerator parameters.

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