# Digital Low-level RF Test at Diamond Booster LLRF9 demo, March 16–20, 2015

D. Teytelman<sup>2</sup>, et. al.

<sup>2</sup>Dimtel, Inc., San Jose, CA, USA

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DLS 1/16

# Outline









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DLS 2/16

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#### LLRF9 Introduction

# LLRF9 System



- A single 2U chassis for oneand two-cavity RF control;
- 9 input RF channels, 2 RF outputs;
- Tuner motor control via RS-485/Ethernet/EPICS;
- External interlock daisy-chain;
- Two external trigger inputs;
- Eight opto-isolated baseband ADC channels for slow interlocks.



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- LLRF9 Introduction
- Demo Setup and Schedule







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### Demo Setup

• Set up LLRF9 to run the booster RF with the following signals:

- RF reference (500 MHz)
- Three cavity probe signals (500 MHz)
- Cavity forward signal (500 MHz)
- Cavity reflected signal (500 MHz)
- Drive output (500 MHz)
- Interlock input (TTL)
- Ramp trigger (TTL)
- Used EPICS interface to control cavity tuning;
- LLRF9 drive was connected to RF Safety Crate (113S) to maintain interlocks;
- Bypassed existing LLRF chain, RF Safety Crate output connected directly to preamplifier (222S).

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5/16

#### Progress

- Monday
  - Connected LLRF9 to inputs only, established signal levels and transferred calibrations;
  - Connected drive output, configured feedback loops;
  - Established closed-loop operation in CW mode.
- Tuesday
  - Interfaced LLRF9 tuner control loops to booster motor control;
  - Established closed-loop operation of tuner and field balance loops.
- Wednesday
  - Transitioned to closed-loop operation with ramping and beam;
  - Characterization of open and closed-loop spectra.
- Thursday
  - Step response measurements;
  - System set up from scratch by Alun Watkins.
- Friday
  - Performance testing;
  - Discussion.

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6/16



- Measured from setpoint to the cavity probe;
- Feedback block in open loop has no dynamics, just gain and phase shift;
- Open loop cavity response;
- Fit resonator model to extract gain, loaded *Q*, detuning, delay, phase shift at ω<sub>rf</sub>;
- Faster than expected gain roll-off above the resonance.

7/16



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DLS 7/16



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- Negative feedback for the π mode is positive for the parasitic mode;
- This positive feedback limits direct loop gain;
- The simplest way around the issue is to use digital delay to equalize the modal phase shifts (230 ns).



8/16



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Image: A matrix



DLS 8/16

# Proportional Loop Gain and Delay



- Set up minimum delay and equalized transfer functions for identical 3 dB closed-loop peaking.
  - Minimum delay: peak gain at RF is -9.2 dB, gain margin 12.3 dB
  - Equalized: peak gain at RF is +8 dB, gain margin 11.8 dB, phase margin 88 degrees
- More sophisticated parasitic mode suppression methods can improve the performance only slightly, around 2-3 dB.



9/16

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- Measured from setpoint to the error signal;
- Quantifies closed-loop disturbance rejection vs. frequency offset from f<sub>RF</sub>;
- Proportional and integrator loops produce high rejection at low frequencies;
- Magnitude on log-log scale, field setpoint of 1 MV.

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- Use ramp start signal to trigger waveform acquisition;
- Ramp profile loaded with a 10% amplitude step (200 to 220 kV);
- Some coupling between amplitude and phase;
- All input channels are captured on the same trigger, observing reflected power here;
- Characterized a 5 degree phase step as well.



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Frequency offset input, IQ circles, decibel radius scale



- Input signal at -60 to 0 dBm in 10 dB steps,  $\approx$  1 Hz offset;
- Log scale polar plot ( $r = 20 \log_{10}|x|$ );
- Center offset, more prominent at low amplitudes, is due to RF feedthrough (coupled from the reference channel);
- Can numerically remove the offsets;
- Good linearity (uncorrected for synthesizer errors), consistent offsets at -73 dBFS.



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- Similar to the test at DLS with several modifications:
  - Reference level at +10.5 dBm vs. +8 dBm at DLS;
  - Input power level monitored by a spectrum analyzer;
  - 5 dB steps.
- Center offset correction;
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# Single Channel Phase Noise



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14/16

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- 9 internal sensors on cold plate: 6 NTCs, 3 DS18B20 digital sensors;
- Three temperature stabilization loops using thermoelectric coolers;
- Two external sensors, in air and attached to chassis;
- Tight stabilization of in-loop sensors;

• Residual sensitivity of out-of-loop sensors is 0.09–0.12 °C/°C.



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- Demonstrated powerful user interface tools necessary for fast station configuration;
- Demonstrated field control at forward power 60 W to 60 kW;
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16/16